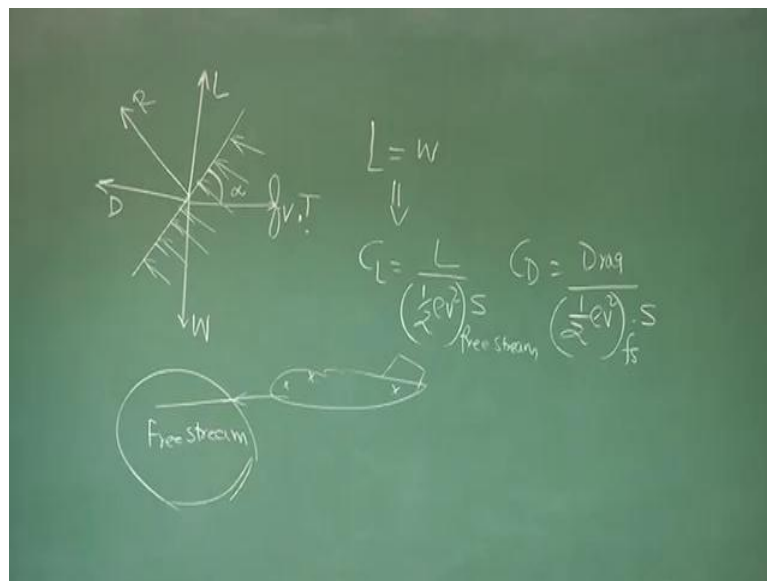


NOC: Introduction to Airplane Performance
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Lecture - 06
Drag Polar

See, we were discussing about George Cayley's explanation for generation of lift.

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We just quickly revise, so that we can understand few things better. Remember, ((Refer Time: 00:25)) this is the plate and if I move this plate at an angle with respect to the speed. And this angle, because of this angle that there will be a pressure from the air outside as we moves like this and that will get translated into force, because of this area and there will be normal force acting on this body.

So, I represent this as, this is the pressure, because of air as it moves through the air and resultant of this I can write this is R, the reaction and one component perpendicular to velocity, we call it lift. Another component which is opposing the velocity called drag and this lift is supposed to balance the weight and if I put an engine which gives thrust.

So, this thrust is supposed to balance the drag, so that I can move like this which is typically we will see soon, we will be defining this flight as a cruise flight. But, let us understand first that if lift has to balance the weight. Then, what is this lift? This lift is generated, because there is an angle between the velocity vector and the surface and this

angle we call let say alpha, this lift definitely will depend upon the speed, it will depend upon the area of this plate.

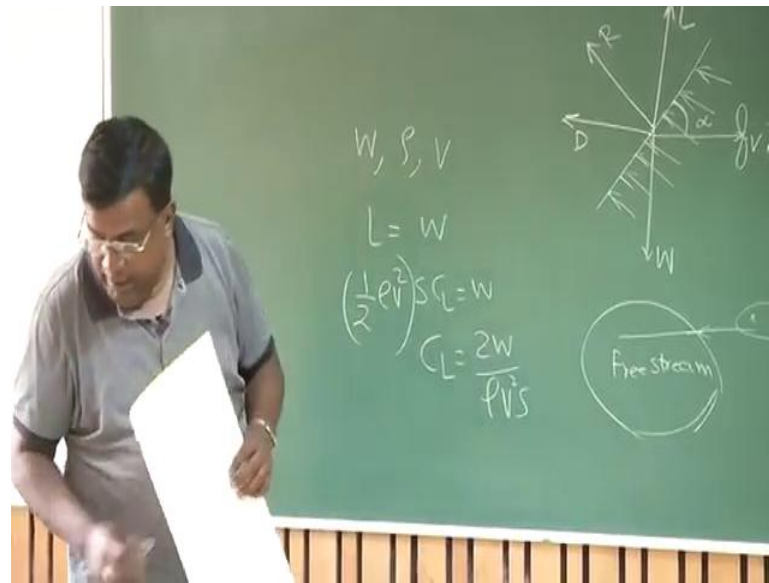
When it comes to the area, we also now let us investigate one thing. If I move this plate like this ((Refer Time: 01:58)) or I move the plate like this, both are having the same angle, but which case you think more lift will be there, this way or this way. You see this way or this way? It is obvious that lift will be more when I moving it like this; that means, it is not only the area, but also how the area is laid out with respect to the velocity vector.

If you see, soon we will be defining some term of that, of this piece in terms of aspect ratio. Watch out for understanding, what is the meaning of aspect ratio and before we go for aspect ratio, we will have a relook here and try to see, how do I translate this to a pilot in terms of flying the machine. Because, I always said whatever aerodynamics, whatever flight mechanics we do finally, I have to translate this in terms of a language which pilot can understand.

Then, from here we realize that we will be operating in terms of C_L which is nothing but, lift getting down dimensionalized by dynamic pressure into S reference. And when we say the dynamic pressure, we talked about free stream dynamic pressure, because we realised that the velocity at different points will be different. If it is the aircraft, if it is moving like this, velocity here, velocity here, velocity here or the dynamic pressure here, here, here all will be different.

So, when a non dimensional arrive this, which that equation I take. So, for that we choose free stream condition, the meaning thereby that at this condition if that affect plane by the plates of the body and that is what is half ρv^2 free stream dynamic pressure and S is the reference area. By now, you know that S is the wing area for aircraft. Similarly, C_D we have drag, non dimensionalized wing with dynamic pressure, again free stream and wing area.

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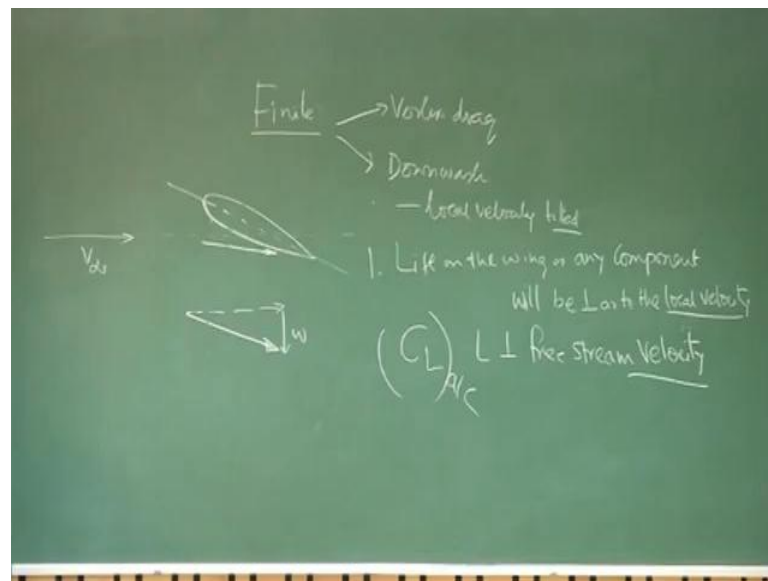
Now, let us see if I want to fly a machine and if I decided to operate in terms of C_L , then I will say for a given weight, given ρ or given altitude and given speed. This lift equal to weight and lift is nothing but, from that expression I see it is half $\rho v^2 S C_L$ equal to weight or C_L equal to $2W$ by $\rho v^2 S$. So, what I know, for a given weight, if I want to maintain lift equal to weight, I must fly at this C_L . But, then how do I generate this C_L ?

I will be turning this plate at an angle or turning the airplane at an angle, so that total C_L of the aircraft is, what is detected by this C_L and how do I do that. Because, I know the airplane have wing, has tail and at angle of a tag, they produce lift, the field air produce lift, the total lift and total C_L should be equal to the C_L required. This part we have already covered, in covering this we also have spoken about the finite wing and quickly, I go through that finite wing we understand.

This is typically a finite wing ((Refer Time: 05:34)), where this is the span, this is the chord here, we have already discussed that. If I joining a line, the leading edge and the trailing edge, the straight line is the chord and this is the span and if it is a finite wing, then what is happening that, at an angle of tag when there is a lift this bottom portion with the high pressure compared to the top portion. So, there are vortices will be formed and that has two effect.

One is, because it is carrying out rotational kinetic energy and that energy is come from the energy of the machine. So, the machine will lose energy or say increase drag and that is termed as vertex drag or lift induced drag and second thing, as the vertices form like this, they induce a downwash in the downward direction. The meaning thereby, if this is the free stream velocity, as it comes close to the aircraft it is velocity vector gets tilted, because of downwash component. So, if I try to draw that...

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So, finite wing before I draw anything, quickly I should have my think be clear. One is vertex drag or lift induced drag, another component is it is induced downwash. So, so the local velocity is tilted, just to draw a diagram on this. Let us see, this is the wing and this is the free stream speed or velocity, as it comes close there is a downwash. So, the velocity vector no more remains straight like this. They also get tilted like this and this tilt if I try to draw that is nothing but, this is the free stream and this is the downwash denoted by w , then this is the resultant velocity vector which comes because of the downwash.

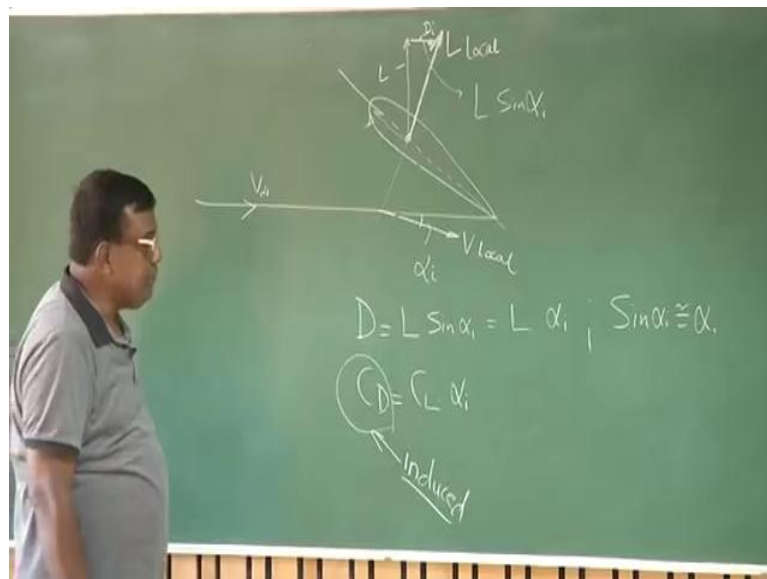
Please note that, this is the free stream velocity and this free stream velocity gets super impose with the downwash, because of wing to vertices and the velocity vector get tilted. So, local velocity vector is different than the free stream velocity vector. Now, the question is, when I try to find lift and this wing, the lift will be perpendicular to the local

flow condition. But, we define drag and lift for the whole airplane based on free stream condition, this is very important.

This is to be noted down, the lift on the wing or any component will be perpendicular to the local velocity. However, C_L of the whole aircraft when I try to write, the C_L or the lift when I try to model it, I should ensure that, that lift is perpendicular to free stream velocity. And by now you know, the local velocity and free stream velocity they are not in same direction, because of downwash near the wing or near any other component.

In this case we are discussing downwash, because of the wing to vertices that is, as these vertices go like this, they induced the downwash. So, let us try to use this understanding and try to get an approximate expression for the induced drag.

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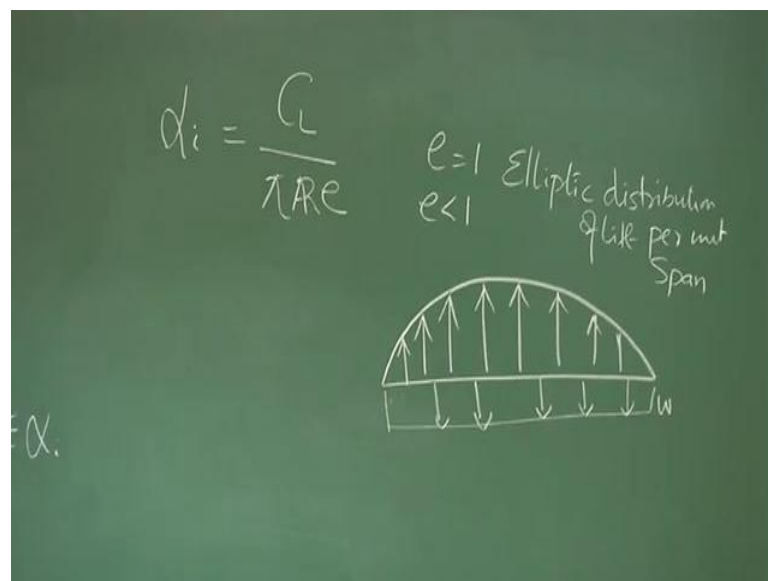
Let us say, this is the left of the... This is the wing and this is your free stream velocity direction and because of downwash, this direction has changed the local, v_{local} . Now, here if I try to draw lift, I know this will be perpendicular to the local flow condition. This lift seen by the wing will be perpendicular to the local flow condition, not to v_∞ and this angle is called... This angle that tilt in the velocity vector which is called induced angle of a tag.

Who were the induced this? It is induced by the downwash. Why downwash has come? Because of the vertices. Why vertices have come? Because of pressure difference in the

bottom and the top position and why do we need a pressure difference, because I want lift. So, it is alpha induced. Now, since I want to define lift and drag, see if I want to write lift I have to resolve this lift which I will call it local, for clarity that should be perpendicular to the free stream direction or the overall aircraft.

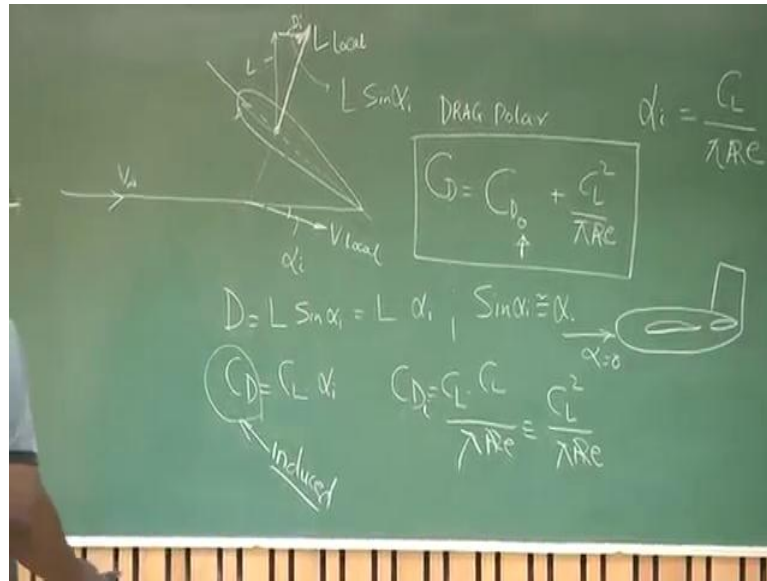
So, if I take the component, so this is the lift and this is the drag, so if I now try to write the drag, you see this will be $L \sin \alpha_i$, this component. I write D_i this is nothing but, $L \sin \alpha_i$ and for a small angle, I can write this as $L \alpha_i$ that is of course, for small angle you know $\sin \alpha_i$ approximately equal to α_i . Similarly, if I, I can write this equivalently C_D equal to C_L into α_i , where C_D when I am writing like this, please understand I am talking about induced drag coefficient, because it is coming from the lift.

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And from theory of incompressible flow, for elliptic distribution one can show that α_i can be approximated as C_L by π aspect ratio e . Of course, e is 1 for elliptic distribution of lift per unit span that is, if I draw it, if I... This is typically elliptic distribution of lift, any standard textbook you can get this information in detail and the bottom I am writing those downwash component and that denoted by w . And of course, e is less than 1 for anything which is not non elliptic. Mostly, we have non elliptic distribution.

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Now, if I substitute this here, so what I get, C_D equal to C_L into C_L by π aspect ratio e and that is equal to C_L square by π aspect ratio e . So, this is nothing but, C_{D_i} , C_{D} induced. So, now, for a wing what we see. For a wing if I want to find total C_D , I know total C_D will be what. One part is induced because of lift, which is given by C_L square by π aspect ratio e and what about the other part. Suppose, this is the wing or further we might have, this is the airplane.

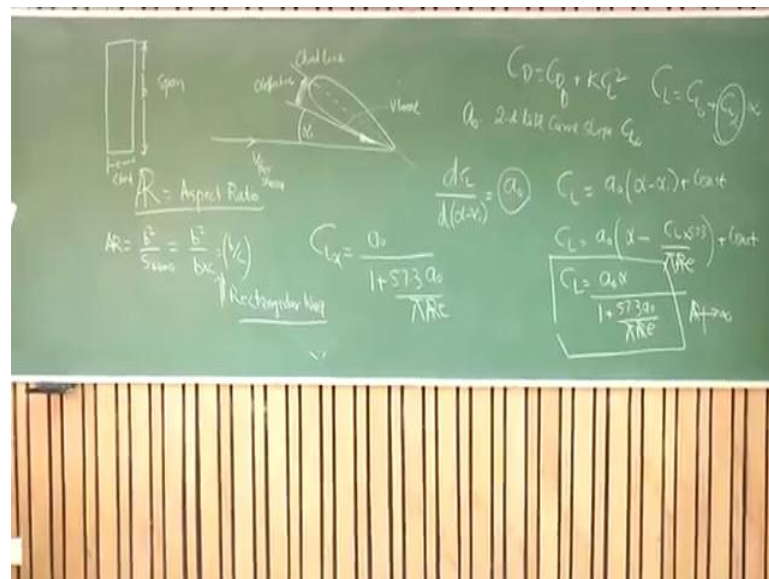
As I am along the air to flow over the wing at α equal to zero, so there will be lot of resistance because of skin friction. Depending upon how stable it is, the skin friction value will change. There could be flow separation at different points, so therefore, pressure drive because of flow separation, so a typical resistance which will be at α equal to zero and typical resistance because of lift and the typical resistance for α equal to zero.

We call parasite drag, which are dependent on the flow condition, which is a subsonic, low subsonic, supersonic, very high speed depends upon, what is the geometry of the airplane. You will know, the aerodynamic is something called Reynolds number, which talks about ratio of inertia of the viscous force, that is if it is a low Reynolds number, then we expect to have more viscous effect. So, accordingly to that, this $C_{D_{naught}}$ will be decided and once we say $C_{D_{naught}}$, this $naught$ means that C_D at zero lift.

For a symmetric aerofoil, it is good enough to say C_D at α equal to zero. For cambered aerofoil, we define this you write C_D at C_L equal to zero and as we progress and see that, some time we try to represent this drag coefficient using C_D minimum also. Those are not referred detail, at this present only understand that the drag coefficient will have two component. One because of parasite drag, ((Refer Time: 16:16)) and another lift induced drag and this representation is known as drag polar.

Whenever you finalize the design, when aircraft is like tested, everything is done, then this has to be estimated and every aircraft is bench marked with a given drag polar under different, different flight conditions. So, this is one of the contribution of finite wing, that because of finite wing there is vertices, because of vertices there are drag, induced drag and because of vertices, they downwash which will also change the lift curve slope or C_L α of the wing. Let us see, how that happens. Let me draw this diagram.

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So, this is typically let us say this is a wing and this is a free stream velocity. As it comes here the wing there is a downwash, because of wing tilt vertices, the velocity vector gets tilted downward. So, this is the local velocity direction and this is the chord line, all these thing you are now familiar and this is the angle, which I call it alpha effective. Because, as far as this wing or the body is concerned, all the lift generation will happen because of this angle, because come back to the John George Cayley, where the lift will depend

upon the angle between the velocity vector, local velocity vector and the surface or the chord line in this case.

So, this is $\alpha_{\text{effective}}$ and α is the induced angle of tag. So, now, we understand one thing if I denote A_0 as 2D lift curve slope, that is lift curve slope which is typically $C_L \alpha$ represented by $C_L \alpha$. What is the meaning of this 2D lift curve slope? That we are assuming that span is infinite, so there are no α_i , because if it is infinite; that means, there are no wing tip, it is not a finite wing. So, there only a wing to vertices, so there is only a wing downwash, so there are no α_i , so that is what is a 0.

So, if I now write $d C_L$ by $d \alpha$ minus α_i , this should give me a 0. Because, I have taken out α_i from the angle, this slope when I am writing C_L versus $\alpha_{\text{effective}}$, which does not take α_i , α_i has been taken out, the effect is taken out. We are talking about this, so this should be the A_0 , if that is a A_0 , then I can write C_L equal to A_0 minus α_i plus constant.

So, C_L I can write as A_0 , for α_i I put the expression which I have written earlier which is C_L by π aspect ratio e . I multiplied by 57.3 to convert this value from radian to degree, then plus constant. So, if I now manipulate this, I do some algebraic adjustment, I can find that C_L equal to A_0 by $1 + 57.3 A_0$ by π aspect ratio e or I can write $d C_L$ by $d \alpha$ equal to A_0 divided by $1 + 57.3 A_0$ by π aspect ratio e .

Let us see, again you come back here. What was a 0? A_0 is the lift curve slope for an aerofoil, that is 2D value; that means, the 2D value does not have any α_i . So, when I try to find the slope C_L and angle of a tag, I am eliminating or taking out the contribution of α_i . So, if I take this slope, this should be A_0 . Now, from here I write C_L equal to this and I get an expression C_L equal to this A_0 minus α_i plus $1 + 57.3 A_0$ by π aspect ratio e , 57.3 I put to convert radian to degree.

What is the message here? If I have got aerofoil lift curve slope, let us say 0.1 per degree, it is degree that is per I am talking about. If I want to really calculate C_L , what I have to do, I have to use that value, put α in degree and add such value A_0 here, so from 2D value I will get 3D value. In this whole expression, there is one term which I am being writing A that is the aspect ratio. We need to know, what is this aspect ratio?

Remember, we will go back again, if this is the plate ((Refer Time: 23:08)) and I am flying like this, as for as George Cayley the lift will be... Because, there is an angle between the velocity vector and the surface and the lift depends upon the reaction which depends upon velocity, area, density, etcetera, etcetera. If it depends upon area, then whether it goes like this or it goes like this they should be same, but they are not same.

We know that lift, for generating lift I should fly like this. Very simple way to get an understanding of it, remember when I am flying like this I can assume that it is composed of so many aerofoils like this. But, if I am flying like this, aerofoil which are not as large as aerofoil like this, because why aerofoil, because the pressure difference will come because of contour of the aerofoil. Like here, if I am flying like this, so many aerofoils, so the contour will get, effect will get added and we get lift.

To make sure that you are flying like this, we also define sometime call aspect ratio and that gives us a field, which way I am orienting this way or this way. For example, aspect ratio if I draw a wing, if I call this b as span and this c as chord, aspect ratio will define as b square by S wing. For a rectangular wing, it automatically becomes b square by b into c , so it becomes b by c , for rectangular plane form wing, rectangular wing which I mean plane form.

Now, see if this is the wing, if that span is increased to infinity what will happen to the aspect ratio. So, aspect ratio also will become infinite. If aspect ratio becomes infinite here, what happens here? If aspect ratio becomes infinite very large, then this term will become 0, so in that case the C_L will be same as C_L what you get from 2D or coming here, the C_L alpha of the whole wing will be same as C_L alpha of the aerofoil, that is it will now behave like a 2D.

So, if you want to get larger C_L alpha, it is better to have larger aspect ratio. By there is a problem of larger aspect ratio, one of the problem is if it is very large aspect ratio wing, how do you balance the weight of the wing and there are other issues will come, as we progress we will understand. In the not sale, whole effort here is towards making one thing very clear that, if you have a finite wing it will give induced drag and there, because of the induced drag your drag efficient will have C_D parasite or zero lift drag plus $K C_L$ square.

This typically follows a parabolic form and also the lift curve slope or $C_L \alpha$ of the wing will also be reduced as compared to $C_L \alpha$ of the aerofoil. If you understand this, then we have understood, what is minimum required for and using this concept for performance analysis. Why do I need the relationship between C_L and α ? Remember, if we write $C_L = C_{L0} + C_L \alpha$, why do you require this, because to maintain lift equal to weight, we need some C_L which will be given by the lift equal to weight equation.

But, for a pilot he has to generate that C_L , so he has to turn the airplane by some angle of attack, which will be dictated by this relationship. And for finite wing, we were trying to understand with aspect ratio, how $C_L \alpha$ of the wing is going to change. So, this is good enough of understanding for us to use this first performance analysis. We may most likely be going to start with the cruise performance next.

Thank you.