

Advanced Composites
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Lecture – 12
Transformation of Stiffness and Compliance Matrices

Hello, welcome to Advanced Composites, today is the last day of the second week of this particular course. Yesterday, we just developed relation between stresses and strains in a specially orthotropic material loaded in a plane stress condition, in a situation, in a general reference frame. So, there we were not specifically aligned to a particular material axis system, we were just making sure that the material is orthotropic. And it is thin and because it is thin, it will have a plane stress condition and for that condition the relationship between stresses and strains in a general x y coordinate system.

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$s \equiv \sin \theta$
 $c \equiv \cos \theta$

$$\{\sigma\}_{xy} = [\bar{Q}] \{\epsilon\}_{xy}$$

$$[\bar{Q}] = [T_1]^{-1} [Q] [T_2]$$

$$\bar{Q}_{11} = Q_{11} c^4 + Q_{22} s^4 + 2(Q_{12} + 2Q_{66}) s^2 c^2$$

$$\bar{Q}_{22} = Q_{11} s^4 + Q_{22} c^4 + 2(Q_{12} + 2Q_{66}) s^2 c^2$$

$$\bar{Q}_{12} = (Q_{11} + Q_{22} - 4Q_{66}) s^2 c^2 + Q_{12} (c^4 + s^4)$$

$$\bar{Q}_{16} = (Q_{11} - Q_{12} - 2Q_{66}) c^3 s - (Q_{22} - Q_{12} - 2Q_{66}) c s^3$$

$$\bar{Q}_{26} = (Q_{11} - Q_{12} - 2Q_{66}) c s^3 - (Q_{22} - Q_{12} - 2Q_{66}) c^3 s$$

$$\bar{Q}_{66} = (Q_{11} + Q_{22} - 2Q_{12} - 2Q_{66}) s^2 c^2 + Q_{66} (s^4 + c^4)$$

We had expressed this sigma with respect to x y coordinate system equals Q bar matrix times the strain vector with respect to x y coordinate system. And to recap Q bar matrix is nothing but inverse of transformation matrix T 1 times Q matrix times transformation matrix T 2.

So, we know what exactly T 1 matrix is. So, we can take its inverse, we know what is T 2 matrix and if we do all the computation the relationship between Q bars and Q S come out like this. So, Q 11 bar equals Q V 1 1 times cosine 4 theta, C means cosine and S

means $\sin \theta$. So, Q_{11} is equal to $Q_{11} \cos^4 \theta + Q_{22} \sin^4 \theta + 2Q_{12} \cos^2 \theta \sin^2 \theta$.

Similarly, Q_{22} is equal to $Q_{11} \sin^4 \theta + Q_{22} \cos^4 \theta + 2Q_{12} \sin^2 \theta \cos^2 \theta$ and Q_{12} equals $\sin^2 \theta \cos^2 \theta$. So, Q_{12} is equal to $Q_{12} + Q_{11} \sin^2 \theta \cos^2 \theta - Q_{22} \sin^2 \theta \cos^2 \theta$.

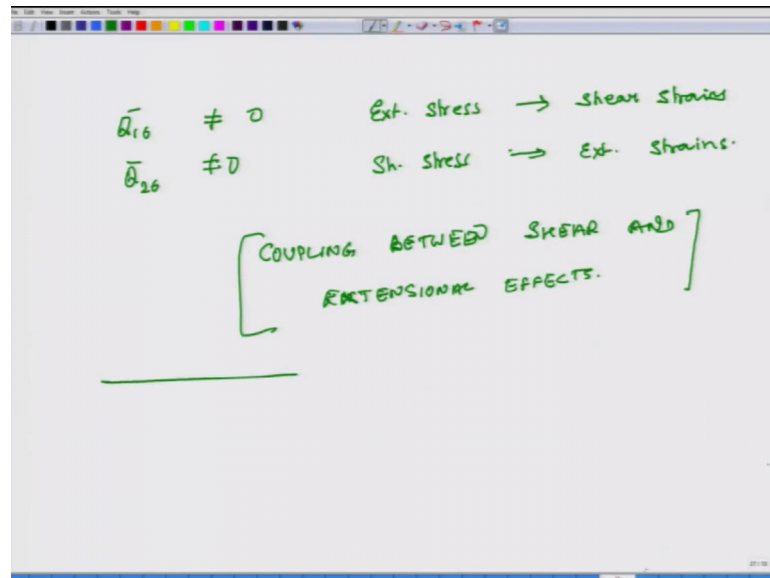
Now, the Q matrix was having Q_{16} and Q_{26} as 0, but in the Q bar matrix Q_{16} is not 0. So, I will write down the expression for that. So, that equals $Q_{11} \cos^3 \theta \sin \theta - Q_{12} \cos^2 \theta \sin^2 \theta - Q_{22} \cos \theta \sin^3 \theta$ and Q_{26} equals same thing.

But, it is $\cos \theta \sin^3 \theta$ minus same terms in this bracket and this is $\cos^3 \theta \sin \theta$ and finally, the expression for Q_{66} bar, so that equals $Q_{11} \cos^4 \theta + Q_{22} \sin^4 \theta - 2Q_{12} \cos^2 \theta \sin^2 \theta + Q_{66} \sin^4 \theta \cos^4 \theta$ ok. And we will spend a couple of minutes looking at these expressions and I will make some observations Q_{11} and Q_{22} and also Q_{12} their values do not change if I change the value of θ from θ to $-\theta$.

How are they dependent on θ ? They are dependent on $\cos^4 \theta$. So, if change from $\cos^4 \theta$ to $\cos^4(-\theta)$ it is the same value $\sin^4 \theta \cos^4 \theta$. The same is also true for Q_{66} , it is also true for Q_{66} , its value also does not change if I switch my θ to $-\theta$; so if θ is 30 degrees and in the other case if it is minus 30 degrees. So, values of Q_{11} bar Q_{22} bar Q_{12} bar and Q_{66} bar they do not change they remain same.

But so, these are even functions of θ . So, these are even in θ , this is also even in θ , but Q_{16} bar and Q_{26} bar let us look at these. So, when I change from θ degrees to $-\theta$ degrees $\cos^3 \theta$ does not change because cosine of positive θ and negative θ is the same. But, $\sin \theta$ changes the $\sin \theta$ changes to negative $\sin \theta$ similarly the $\sin^3 \theta$ also changes. So, for this reason Q_{16} bar.

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And \bar{Q}_{26} are odd functions in θ the other thing I would like to say is that because \bar{Q}_{16} and \bar{Q}_{26} they are not necessarily 0. This mathematically implies that extensional strains or extensional stresses they can generate shear strains. And shear stresses they can generate extensional strains and vice versa.

This was not the case for specially thermo orthotropic material because, \bar{Q}_{16} and \bar{Q}_{26} are 0, but when we move to the land of general orthotropy, then there is coupling between shear and extensional effects ok.

So, if you have a rectangular sample and you pull it, it will not only become longer, but it will also deform and its angles at the corners will change from 90 degrees to something different. And it is important to note that the direction of this coupling is sensitive to θ . So, if you change from positive θ to negative θ , its direction reverses, its direction reverses because \bar{Q}_{16} and \bar{Q}_{26} are odd functions of θ .

So, it is important to get our conventions right. So, whenever we measure θ this is the convention we follow otherwise, we will not get our shear strains and things like or we will not get our solutions correct because of the sensitivity of \bar{Q}_{16} and \bar{Q}_{26} to the direction of θ . So, we should be clear on our conventions which are consistent with the conventions we have used in this formulation. So, I can once again write.

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$$\{\sigma\}_{xy} = [\bar{Q}] \{\epsilon\}_{xy}$$

$$\Rightarrow \{\epsilon\}_{xy} = [\bar{S}] \{\sigma\}_{xy} \quad \bar{S} \rightarrow \text{Compliance matrix}$$

$$\bar{S}_{11} = S_{11} c^4 + S_{22} s^4 + (2S_{12} + S_{66}) s^2 c^2$$

$$\bar{S}_{22} = S_{11} s^4 + S_{22} c^4 + (2S_{12} + S_{66}) s^2 c^2$$

$$\bar{S}_{12} = (S_{11} + S_{22} - S_{66}) s^2 c^2 + S_{12} (c^4 + s^4)$$

My stress vector in x y coordinate system as Q bar matrix times a strain vector if I multiply both sides of this equation by inverse of Q bar matrix then I can express strain in terms of a stiff in terms of a compliance matrix and stress. So, this gives me strain vector is equal to S bar matrix times a stress vector ok. So, stress bar is compliance matrix and it is nothing but inverse of Q bar.

So, the mathematical relation between different Q bars and S bars is this. So, this is equal to $S_{11} C^4$ plus $S_{22} S^4$ plus $2 S_{12}$ plus $S_{66} S^2 C^2$. S_{22} bar equals $S_{11} S^4$ plus $S_{22} C^4$ plus 2 this entire thing $S^2 C^2$. And S_{12} bar equals S_{11} plus S_{22} $S^2 C^2$ plus S_{12} times C^4 plus S_{66} .

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$$\begin{aligned} \bar{S}_{11} &= S_{11} c^4 + S_{22} s^4 + (2S_{12} + S_{66}) s^2 c^2 \\ \bar{S}_{22} &= S_{11} s^4 + S_{22} c^4 + (2S_{12} + S_{66}) s^2 c^2 \\ \bar{S}_{12} &= (S_{11} + S_{22} - S_{66}) s^2 c^2 + S_{12} (c^4 + s^4) \\ \bar{S}_{66} &= 2(2S_{11} + 2S_{22} - 4S_{12} - S_{66}) c^2 s^2 + S_{66} (c^4 + s^4) \\ \bar{S}_{16} &= (2S_{11} - 2S_{12} - S_{66}) c^3 s - (2S_{22} - 2S_{12} - S_{66}) c s^3 \\ \bar{S}_{26} &= () s^3 c - () s c^3 \end{aligned}$$

And then S_{66} is equal to twice of twice of S_{11} plus 2 of S_{22} minus 4 of S_{12} minus S_{66} . Cosine square sin square plus S_{66} cosine 4 plus sin 4 S_{16} bar equals $2 S_{11}$ minus $2 S_{12}$ minus S_{66} cosine cube theta sin minus $2 S_{22}$ minus $2 S_{12}$. So, these are small error here this is 2 in bracket ok. So, it is 2 minus S_{66} cosine sin cube and S_{26} bar equals the same thing times sin cube cosine minus this thing sin cosine cube.

So, once again we see that S_{11} bar S_{22} bar S_{12} bar and S_{66} bar they are all even in theta. While these 2 guys S_{16} bar and S_{26} bar they are all odd in theta. So, it is important to understand it, lastly I will write the stress strain relationships between stress and a strain relationships in terms of engineering constants. So, those relationships are.

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$$\begin{Bmatrix} \epsilon_x \\ \epsilon_y \\ \gamma_{xy} \end{Bmatrix} = \begin{bmatrix} 1/E_x & -\nu_{xy}/E_x & -m_x/E_L \\ -\nu_{xy}/E_x & 1/E_y & -m_y/E_L \\ -m_x/E_L & -m_y/E_L & 1/G_{xy} \end{bmatrix} \begin{Bmatrix} \sigma_x \\ \sigma_y \\ \tau_{xy} \end{Bmatrix}$$

$\left. \begin{matrix} m_x \\ m_y \end{matrix} \right\} \text{CROSS COEFF.}$

$\begin{matrix} E_x & G_{xy} \\ E_y & m_x \\ \nu_{xy} & m_y \end{matrix}$

 \rightarrow

$\begin{matrix} E_L & \nu_{LT} \\ E_T & \delta \\ G_{LT} \end{matrix}$

Given here epsilon x epsilon y gamma x y equals 1 over E x minus nu x y over E y minus m x over E L minus nu x y over E x 1 over E y and minus m by over E l, and this is minus m x over E L minus m y over E L and 1 over G x y times sigma x sigma y tow x y.

So, these are the stress strain relationship for a generally orthotropic material which is in a state of plane stress in terms of engineering constants you know engineering stiffness constants of the material which are E x E y E L m x m y and so, on and so, forth. So, here m x and m y, if these terms were 0 then they will not be any shear extensional coupling. So, these are the cross coefficients these are called cross coefficients and what do they do? They once again they couple the extensional response to the shear response and vice versa.

The relationships for E x E y nu x y G x y m x m y; so these 6, we have already explained these relationships in our previous course. So, you please go and refer to that and you will find the relation so, that E x E y nu x y g x y m x and m y all of these things can be calculated in terms of E L E T G L T nu L T and the transformation angle theta.

So, even though these are 6 constants, but they can be expressed in terms of is 4 fundamentally Independent constants for this orthotropic material under plane stress state.

So, that concludes our discussion for today and also the content which I wanted to cover in this week. I hope you have a wonderful weekend if you have any questions please do send us emails and next week we will move on to another topic where we will start discussing the behavior of laminates in terms of these constants and how we can relate stresses and strains in case of laminates.

So, with that I conclude our discussion. Have a great day and a wonderful weekend.

Thank you.