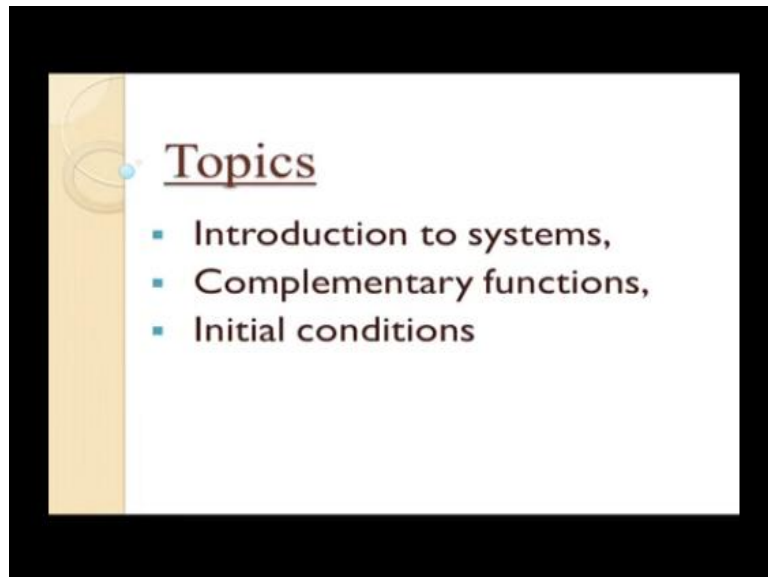


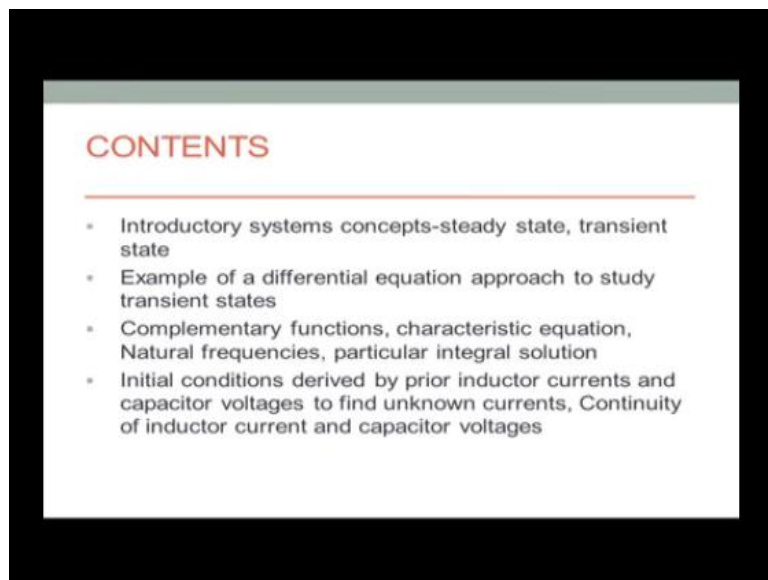
Networks and systems
Prof. V.G.K. Murti
Department of Electrical Engineering
Indian Institute of Technology – Madras

Lecture-11

Introduction to Systems Complementary Functions Initial Conditions
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After having familiarized ourselves with the different types of standard signals we have to deal with normally in system analysis. Let us now introduce ourselves to some elementary system concepts which will be found useful later on in our course. Generally when we are talking about the analysis of systems we would like to assess the dynamic performance of the systems.

And in this context it should be useful for us to remind ourselves of what a steady state of a system means and what the transient state of a system means. When the variables of a system or a network are either constant d c values or are regularly repeating periodic functions of time then the system is said to be under steady state conditions.

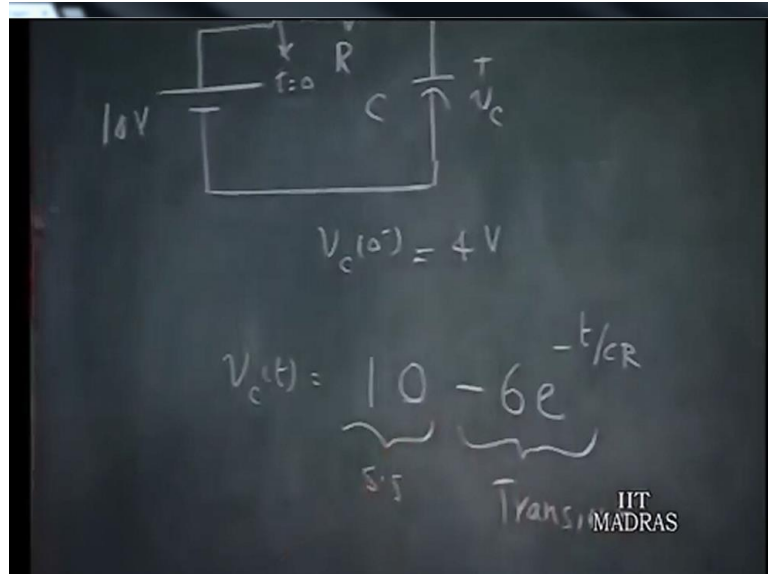
Under sinusoidal circuit theory you deal with systems under steady state conditions where all the voltages and currents are periodic functions are times which are sinusoidal in character. Similarly, in a d c circuit you deal with steady state conditions when all the voltages and currents are constant.

So, once again the system is said to be under steady state when the signals characterizing the system are either constants or regular periodic functions of time. The best way to define the transient state of the system is to say the system is under the transient state when it is not under steady state. There is no other simpler way of doing that.

So, in general on the account of a switching process you open a switch or you close a switch or some system parameter suddenly changes. Then the network transits from 1 steady state to another steady state and the intervening period in the transition between 1 steady state to another steady state is referred to a transient state. And it is the study of the transients which forms the central theme of the analysis of networks and systems that we are going to take up.

Strictly speaking most of the transients take infinite time to die out but in practice as for the engineering approximations are concerned within relatively short time which is 3 or 4 times the time constants involved. We can assume the transients to decay to negligible proportions.

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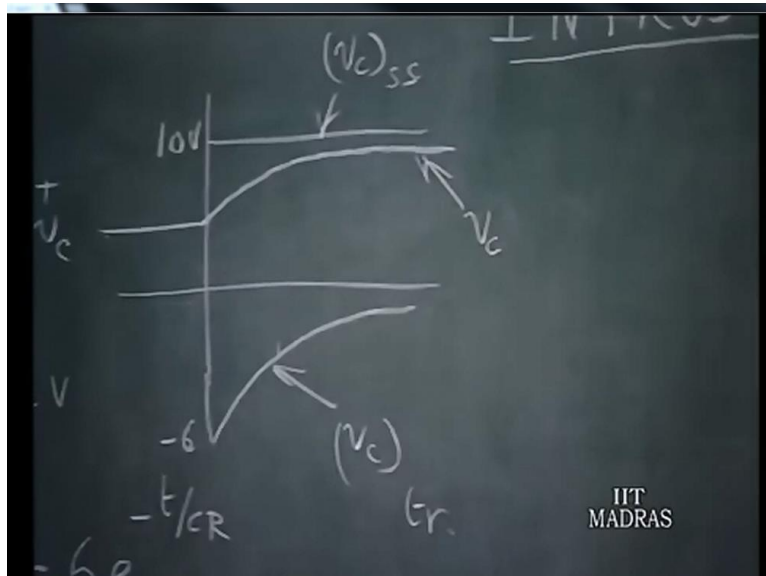
Let me take an example to illustrate this idea suppose I have a 10 Volts. D.C. source connected to a r c circuit with an initial capacitor voltage of 4 Volts and I would like to find out how the capacitor voltage behaves for time t equals 0 onwards if the switch is closed at t equals 0.

Now, the capacitor voltage V_c to start with is 4 Volts ultimately it will reach a voltage of 10 Volts. It gets charged to this 10 Volts therefore the capacitor voltage the steady state in a capacitor is 10 that is the steady state voltage of the capacitor. But at the time of closure of the switch the capacitor voltage is 4 Volts and there is no reason for that voltage to change because there is a resistance here and that absorbs any shock that comes in between this is 10 Volts, this is 4 Volts, this 6 Volts. is dropped across the resistance.

So, initially the value of the capacitor voltage must remain as 4 Volts. Therefore, you have a transient term which is minus 6 and from your elementary knowledge of transient analysis this will be t over $c r$. So, this is an exponential term which decays with time.

Therefore, V_c of t is 10 minus 6 e to the power of minus $t cr$, cr is the time constant of the circuit. This is the steady state part and this is the transient part. So, in going from 1 steady state to another steady state in going from 4 Volts steady state to a 10 Volts steady state you have a transient arising.

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So, the capacitor voltage can be this is 10 Volts, this is d c steady state new steady state of course as 4 Volts and then you have a transient term which has an initial amplitude minus 6 and decays like this.

So, this is the transient component of the capacitor voltage. The sum of these 2 will give rise to a curve like this is the actual capacitor voltage. So, you recognize in this process a steady state value and a transient part and the transient component arises because the old steady state does not match the new steady state. So, therefore there is a transient which bridges this gap.

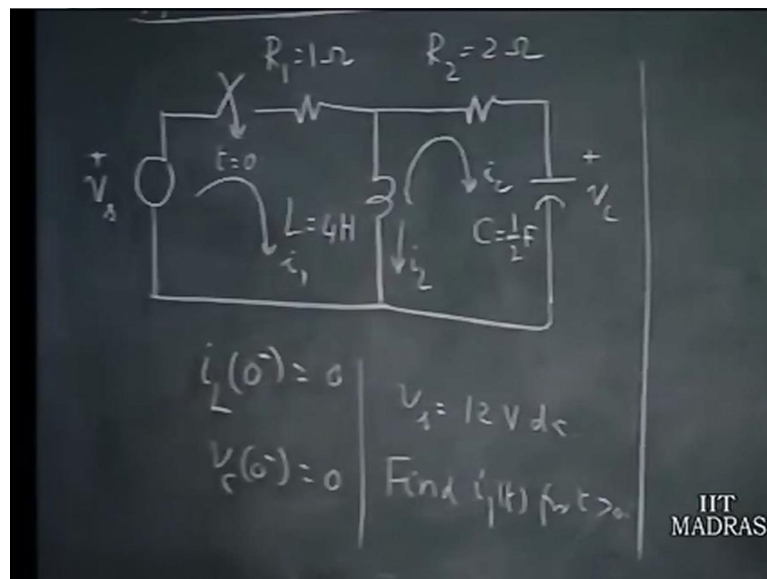
In order to solve for this transients, you have different approaches available. The classical differential equation approach is the most fundamental method. But it is somewhat complicated but nevertheless since it is a fundamental approach because most of the equations of the network are written in terms of differential equations.

Therefore, it is a fundamental approach and since you have studied differential equations in your mathematics courses it would be convenient for us to see how the differential equation approach can be used to study transients in networks of this type.

So, we will illustrate we will use this idea through an example and then later on we will show that some of these associated with the solution of transients through differential equations approach can be overcome using operational methods like Laplace Transform methods at a later point in the course. But to get a feel for the

advantages of Laplace Transforms we must know what the difficulties are in the differential equations approach.

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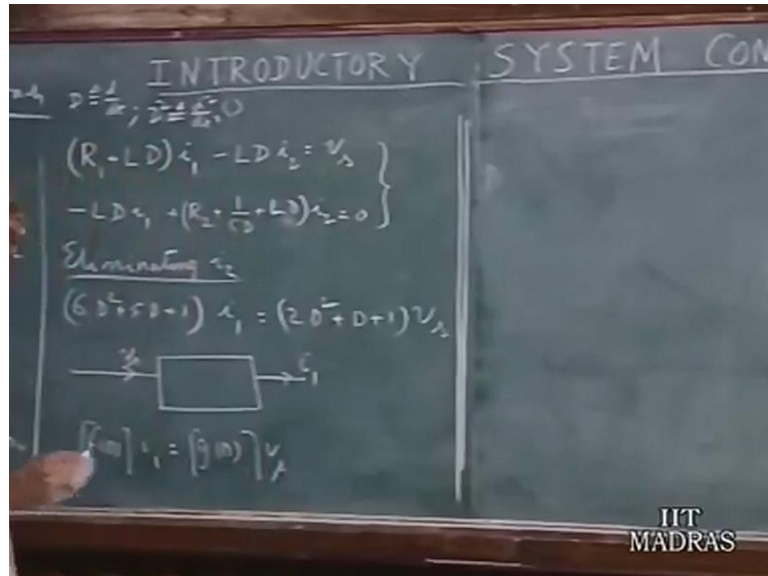
So, let us take an example let us consider this particular circuit to illustrate the differential equation approach. We have an inductor and capacitor in the circuit and the inductor and capacitor provides the initial conditions that are necessary to solve the problem and normally. The initial conditions are given pertaining to a situation before a closure of a switch.

So, let us say $i_1(0^-)$ before the closure of the switch is 0 Amperes and the capacitor voltage before the closure of the switch is also 0. And let us also say that the source voltage is 12 Volts d.c. to solve for this particular solution to solve for the circuit. Let us, take the loop equation approach we have 2 currents i_1 and i_2 in the 2 loops.

We write down the differential equations pertaining to the 2 loop currents to start with and then let us say that in this particular problem you are interested in finding out i_1 . Find i_1 of t for t greater than 0 so this is the solution.

So, let me write down the differential equations for the 2 loops. You have for the first loop $R_1 i_1 + L \frac{di_1}{dt} - i_2$ must be equal to V_s .

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And this can be written as r_1 plus l derivative operator operating on i_1 because derivative operator d is equivalent to $d i_1$ by dt . D times i_1 is $d i_1$ by dt minus l d operating on i_2 equals V_s . That's the first equation where by definition d by definition is d up on dt .

Similarly, d square by definition is d the second derivative of the particular quantity. Now, for the second loop suppose you take the voltage drops in the direction of the loop current i_2 . We have r_2 times i_2 1 over c d that is the integral of the current i_2 divided by c . That's the voltage V_c plus d by dt 1 times d by dt of i_2 minus i_1 is the voltage drop across the inductance in this direction.

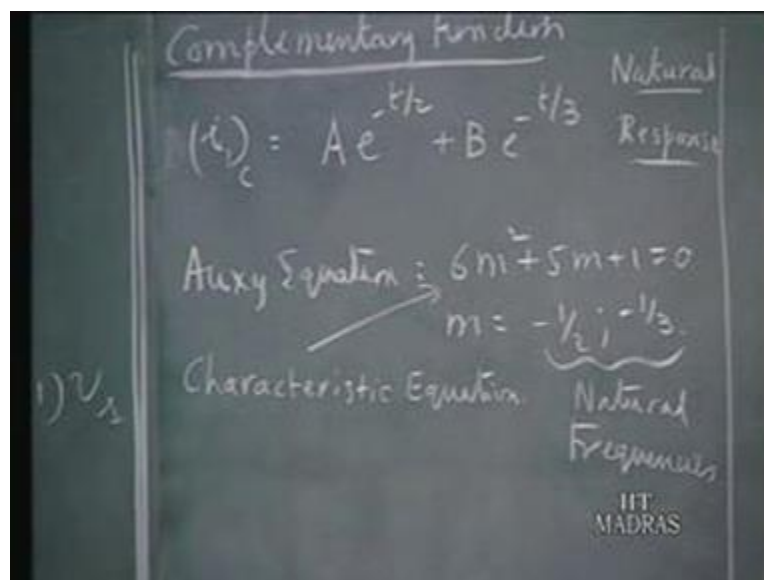
So, if you write that respective terms you get r_2 plus 1 over c d plus l d operating on i_2 that is equal to 0 because this 1 over c d indicates the integral of i_2 dt 1 over c d i_2 means 1 over c integral i_2 dt . That's the voltage across the capacitor so that is what we are having. Now, we are interested in solving for i_1 . Therefore, we have to eliminate i_2 . If they are purely algebraic equations would have multiplied by suitable factors and we would have eliminated i_2 .

The same thing can be done here also recognizing these are derivative these are operator functions but we can manipulate them in the same way as the algebraic factors. So, you multiply this factor by l d and this factor by r_2 plus 1 over c d plus l d and eliminate i_2 in the process. And substituting numerical values you get for this particular circuit eliminating i_2 we have $6d$ square plus $5d$ plus 1 operating on i_1 equals $2d$ square plus d plus 1 operating on V_s .

This is the final differential equation that you have connecting the source voltage and the response quantity i_1 that you are interested in. In system representation, we can put this as an input quantity V_s and the desired output i_1 represented by this fashion. This is characteristic of the type of differential equations we will get in all these problems.

So, this can be put in this fashion an operator function $f d$ operating on i_1 equals another operator function $g d$ operated on V_s . whereas, this is the input this is the output. The output and input are relation are corrected by a differential operators of this type $f d i_1$ operating $f d$ operating on i_1 will be $g d$ operating on V_s . So, this is characteristic of all single input, single output systems. For the solution for this in the classical differential equation approach is done is 2 parts.

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The complimentary function solution this is part of the solution. So, i_1 complimentary will consist of 2 terms depending up on the roots of the Auxiliary equations. So, the Auxiliary equation we have here is $6m^2 + 5m + 1 = 0$. This is the $6d^2 + 5d + 1 = 0$. We substitute use m for d and this is what we get as Auxiliary equation and the values the solutions for this will be m equals minus half and minus one-third.

So, the complementary part of the solution will have an arbitrary constant a multiplied by e to the power of minus t by 2 plus another arbitrary constant b multiplied by

minus t by 3. So, this is the complementary part of the solution which is familiar to you through your elementary course on solution of differential equations.

Now, we have something to say about this now, this complementary solution whatever you are getting is also termed the ports free solution or the natural response of the system natural response because this portion of the response the characteristic of this response this t by 2 and t by 3 minus t by 3 will remain there no matter what source you take what forcing function you take.

Whatever, forcing function you take that portion will remain the same. Therefore, this is inherent to the system and this is a natural response and this equation is called the characteristic equation. Now, it is called the characteristic equation because of the fact that no matter what variable you wish to choose to solve for in the circuit whether you want to solve for i_1 or i_2 or the capacitor voltage or the inductor voltage.

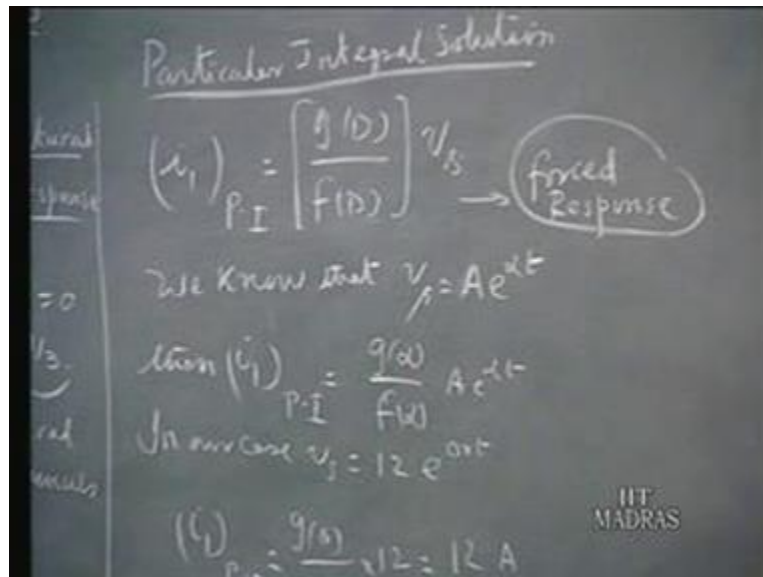
Whatever, you want to do the characteristic equation will remain the same. This you will get; that means this f of d you get the same f of d no matter what you take as the response quantity and so this is something which is characteristic to the system and it is independent of the forcing function that is why it is called characteristic equation.

And the roots of the characteristic equation are the natural frequencies minus half and minus one-third are called are the natural frequencies of the system. So, the complex frequencies present in this particular signal are minus half and minus one-third. They happen to be real in this case but in terms of the general concept of complex frequencies these are the 2 values minus half and minus one-third. They are the complex frequencies for of the system.

They are called the natural frequencies because they are inherent to the system and they arise irrespective of the forcing function that you are having. So, this is the complementary function solution which is obtained from solving the characteristic equation, Auxiliary equation.

We have to of course solve for a and b because they are arbitrary constants. They depend up on the initial conditions.

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But before we proceed further we need to have the particular integral solution. The particular integration solution from your elementary study of differential equations will be obtained as g of d by f of d operating on the forcing function V_s .

This is an operator function we know that if V_s is of the form say e to the power of αt then the particular integral solution is obtained as g of α divided by f of α multiplied by e to the power αt . That's the operator d is replaced by simply the factor α in the exponent that is how it goes. Now, in our case V_s equals $12 \text{ Volts } d.c.$

Therefore, we can take $12 e$ to the power of 0 times t α is 0 . Therefore, the particular integral solution i_1 particular integral solution is $g(0)$ divided by $f(0)$ multiplied by 12 . If you substitute d equals 0 in this equation you have this $f(0)$ is 1 and $g(0)$ is 1 . Therefore, this is 12 particular integral solution is 12 Amperes .

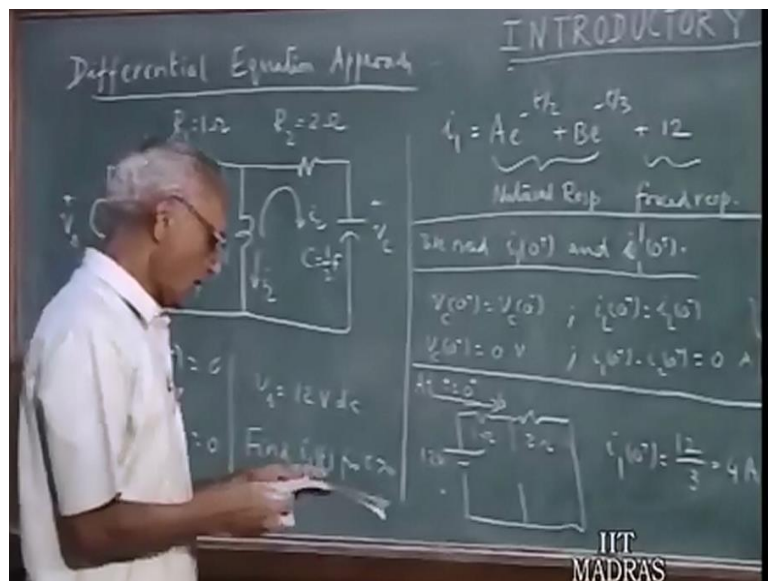
Now, this is also called whatever solution you get here this is also called forced response because this is the response which depends up on this particular input that you are having. This is the V_s forces this kind of response through the differential equation and if complex frequency is present in the forced response it will be exactly the complex frequency that was present in v of s .

If v of s is a has a single complex frequency α then this also will have the solution will also have the complex frequency α . If this has a complex frequency s

this will have complex frequency s . If this has a variety of complex frequencies s_1, s_2, s_3, s_4 then, i_1 particular will also have all those complex frequencies.

So, the force part of the solution has the same complex frequency that was present in the input waveform whereas the complementary solution will have complex frequencies which are inherent to the system. They are called the natural frequencies now we have got the particular integral solution as well as the complementary function solution.

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So, the total solution is i_1 equals $a e^{-t/2} + b e^{-t/3} + 12$. This is the natural part natural response this is the forced response. Now, that we have got the total solution the form of the total solution we have to evaluate these arbitrary constants a and b for that we need to know the initial conditions, from the initial conditions you should be able to find out a and b .

We need 2 conditions so it is convenient in these situations given by 2 conditions on i_1 we need to find out $i_1(0^+)$ plus and the derivative of i_1 evaluated at 0^+ plus $\frac{di_1}{dt}$ evaluated at 0^+ . You can think of any 2 equivalent conditions any 2 conditions dependent conditions but these come naturally and they are convenient to calculate $i_1(0^+)$ plus and $i_1'(0^+)$ plus.

Now, how do we go about it? It is the initial conditions and their reactive elements which provide a link between the situation before the switching operation and after the switching operation. They form the bridge between the conditions in the circuit

before the switching takes place and after the switching takes place. So, it is ultimately related to i_{l0} and V_{c0} .

We assume that V_{c0+} is the same as V_{c0-} normally the capacitor voltage is continuous unless there are impulse currents which we see later. Normally, we can assume this to be true and there's no reason for the capacitor voltage to change suddenly as far as this circuit is concerned and i_{l0+} is the same as i_{l0-} . So, we can say that V_{c0+} is also 0 volts and i_{l0+} which is really $i_{10+} - i_{20+}$.

That i_l equals $i_1 - i_2$ this is also 0. So, this is the information that is given to us and from this information we should be able to manufacture the values of i_{10+} and $i_{1prime0+}$. How do we do that? Now, let us see at $t = 0+$ you have this 12 Volt source and you have r_1 and r_2 . The current in the capacitor inductor is 0.

Therefore, that is almost an open circuit and the capacitor is a short circuit because the voltage across the capacitor is 0. So, you have $r_1 = 1\text{ohm}$ $r_2 = 2\text{ Ohms}$. So, the current i_1 here is 12 divided by 1 plus 2 3 Ohms. Therefore, i_{10+} is 12 up on 3 that is 4 Amperes. That is the initial value of the current 12 up on 1 plus 2 4 Amperes. Now, how about the derivative of the current at $t = 0+$.

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Handwritten equations on a chalkboard:

$$12 = V_s = i_1 R_1 + i_2 R_2 + V_c ; t > 0$$

$$0 = i_1' + 2i_2' + \frac{dV_c}{dt} ; t > 0$$

At $t = 0^+$

$$0 = i_1'(0^+) + 2i_2'(0^+) +$$

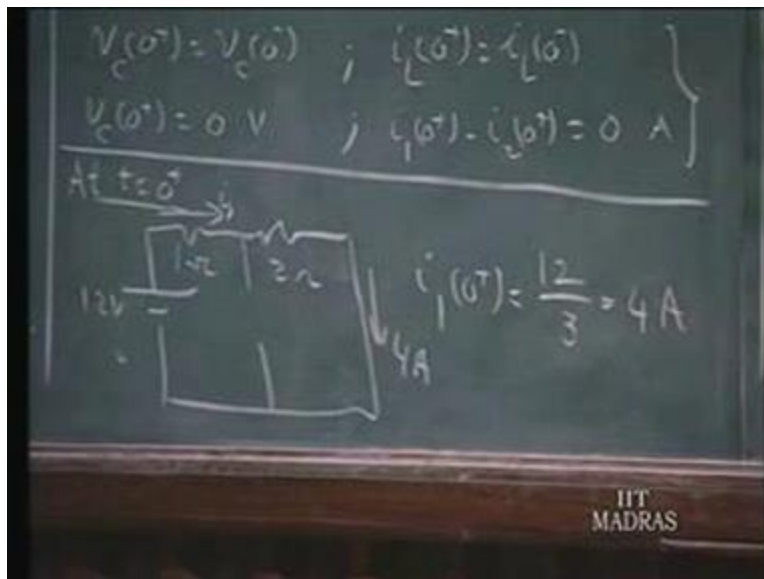
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Now, to that we have to some kind of manipulation from this circuit we can see that V_s equals $i_1 r_1 + i_2 r_2 + V_c$. This voltage equals $i_1 r_1 + i_2 r_2 + V_c$ for t greater than 0. Let us, take the derivative of this is of course 12 Volts. All the time this

is 12 for t greater than 0. Take the derivative of this derivative of this constant is 0. R_1 is 1 Ohm. Therefore, i_1 prime 0 plus 0 does not matter at any time t this is i_1 plus and then this is i_2 plus and i_2 prime times r_2 which is 2 Ohms plus $d v_C / dt$ that is what you are having. i_1 plus i_1 prime plus $2i_2$ prime plus $d v_C / dt$ r_1 being 1 Ohm and r_2 being 2 Ohms right.

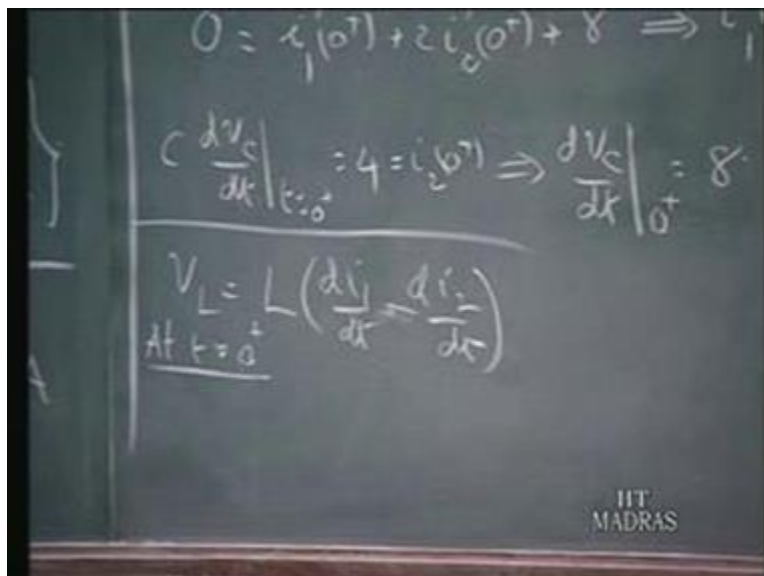
Now, this is true for all values of time greater than 0 at t equals 0 plus this is i_1 prime 0 plus 2 times i_2 prime 0 plus what is the value of $d v_C / dt$ at t equals 0 plus.

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The current in the circuit the current in c here at t equals 0 plus is 4 Amperes. This is 4 Amperes so what does it mean?

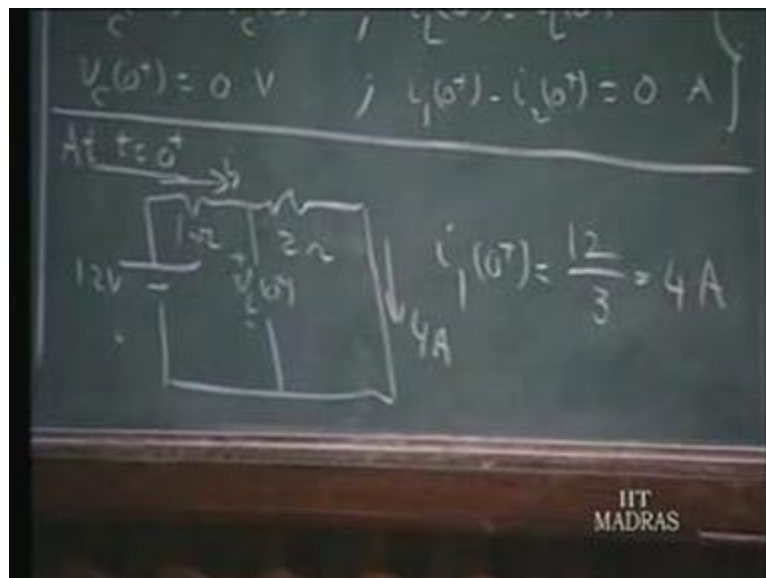
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That $C \frac{dV_c}{dt}$ that is the current in the circuit at $t = 0^+$ equals 4. This is $i_2(0^+)$ plus $i_1(0^+)$ is the same as $i_1(0^+)$ from this we observe that $\frac{dV_c}{dt}$ at $t = 0^+$ plus $\frac{dV_c}{dt}(0^+) = 4$ divided by $2C$ equals half a Farad, C equals half a Farad. Therefore, this is equal to 8 Volts per second. Therefore, this substitute $\frac{dV_c}{dt}$ is equal to 8.

So, this will lead me to a result $i_1'(0^+) + 2i_2'(0^+) = -8$. Now, we need to have another equation this is not enough. Now, we need to add another equation in $i_1(0^+) + i_1'(0^+) + i_2'(0^+) = 0$. What is the voltage across the inductor? $V_L = L \frac{di_1}{dt} + L \frac{di_2}{dt} - L \frac{di_2}{dt}$. That's what we are having.

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At $t = 0^+$ what is the value of the voltage across the inductor. This is equal to $V_L(0^+)$. What is the value of the voltage across the inductor at 0^+ . 2 Ohms and a current i_1 of 4 Amperes. Therefore, 8 Volts the capacitor voltage is 0 so at $t = 0^+$ plus this is 8 Volts.

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$$0 = i_1'(0^+) + 2i_2'(0^+) + 8 \Rightarrow$$

$$C \frac{dV_C}{dt} \Big|_{t=0^+} = 4 = i_2'(0^+) \Rightarrow \frac{dV_C}{dt} \Big|_{0^+} = 8$$

$$V_L = L \left(\frac{di_1}{dt} - \frac{di_2}{dt} \right)$$

$$\text{At } t=0^+ \quad 8 = 4 \left[i_1'(0^+) + i_2'(0^+) \right]$$

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$$0 = i_1'(0^+) + 2i_2'(0^+) + 8 \Rightarrow$$

$$C \frac{dV_C}{dt} \Big|_{t=0^+} = 4 = i_2'(0^+) \Rightarrow \frac{dV_C}{dt} \Big|_{0^+} = 8$$

$$V_L = L \left(\frac{di_1}{dt} - \frac{di_2}{dt} \right)$$

$$\text{At } t=0^+ \quad 8 = 4 \left[i_1'(0^+) + i_2'(0^+) \right]$$

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L equals 4 Henrys and this is i_1' plus i_1' prime 0 plus i_2' prime 0 plus. So, you have another equation from this i_1' prime 0 plus minus I am sorry this minus i_1' prime 0 plus minus i_2' prime 0 plus equals 2. So, you have 2 equations. 1 is i_1' prime 0 plus $2i_2'$ prime 0 plus is minus 8. The other equation is i_1' prime 0 plus minus i_2' prime 0 plus is 2 and the solution for this from these 2 you get i_1' prime 0 plus as minus 4 up on 3 Amperes per second.

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$$\left. \begin{aligned} 3 &\Rightarrow i_1'(0^+) + 2i_2'(0^+) = -8 \\ \frac{V_c}{3L} \Big|_{0^+} = 8 &\Rightarrow i_1'(0^+) - i_2'(0^+) = 2 \end{aligned} \right\}$$

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So, you have $i_1(0)$ is plus 4 Amperes $i_1'(0)$ prime is 4 minus 4 by 3 Amperes per second.
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To solve for A & B

$$i_1(0^+) = 4 \text{ A}; \quad i_1'(0^+) = -\frac{4}{3} \text{ A/s}$$

$$A = 24; \quad B = -32$$

$$i_1(t) = 24e^{-t/2} - 32e^{-t/3} + 12; \quad t > 0$$

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So, you use this information to solve for a and b. So to solve for a and b we use $i_1(0)$ plus equals 4 Amperes and $i_1'(0)$ plus equals minus 4 by 3 Amperes per second. You substitute these values in this expression straight away this value. I will take the derivative of this and time put t equals 0 plus and substitute this value. You solve for a and b you will get the solution a equals 24, b equals minus 2.

And finally, you get the solution as $i_1(t)$ equals 24 e to the power of minus t up on 2 minus 32 e to the power of minus 3 up on 3 plus 12 and this is the solution valid for t greater than 0. That is the final solution.

So, let us see what we can gather from through the example. In the differential equation approach you have 2 partial solutions. The complementary part of the solution and the particular integral part of the solution, the complementary part of the solution is obtained through the solution of the Auxiliary equation or also what is called the characteristic equation. And this characteristic equation is independent of the particular response which we have choosing.

It depends up on the system as such the composition of the system and the various elements. The natural frequency the frequencies that are present in the complementary solution are what are termed the natural frequencies. They are in general complex in our particular case it may have been real but in general complex.

So, these complex frequencies present in the source free response of the complementary solution are called the natural frequencies. This is characteristic of the system it does not depend up on the particular forcing function. On the other hand, the particular integral solution is what is called the force response for the solution and it has all the frequencies which are present in the excitation function or the input function.

The sum of these will be the total solution and in solving for these we need to have information about the initial conditions of the quantity which you are going to solve for. In mathematics generally when you are solve the differential equation these initial conditions for the reason of interest given to you but in problems of this type we do not have those initial conditions given to you straight away on a platter.

What you are given is in a circuit like this some initial conditions pertaining to the regime before the switching operation. From this you must find out the new initial conditions appropriate to t equals 0 plus pertaining to the particular quantity which you are interested in whereas the initial conditions are given in terms of the capacitor voltages and inductor currents.

So, this requires a lot of manipulations as we have seen and this is really 1 of the troublesome aspects of the classical approach of classical differential equation,

approach of the solution of the problems. Because, if you have imagined that you have a n 'th order differential equation here luckily we have only 2 reactive elements.

Suppose, you have got 5 reactive elements the differential equation would have been of fifth order and you need to have 5 initial conditions pertaining to any quantity to which you have to solve for not only the initial value but the first 4 derivatives. Even for first derivative we had so much trouble.

So, you can imagine the type of trouble which you would have had if you had to find out the initial value of the fifth derivative. So, this is really a problem. So, in the classical solution you need to find out the initial conditions appropriate to the particular quantity which you want to solve for and this requires a considerable amount of manipulation.

In this particular example what you have taken we assume the capacitor voltages and the inductor currents are continuous which is normally the case but there may arise situations where the capacitor currents capacitor voltages have to jump from 1 value to another from 0 minus to 0 plus it may have to undergo a jump.

And similarly, the inductor currents may have to have a jump from 0 minus value to 0 plus value. As we have seen in an example when a battery is connected to an uncharged capacitor immediately the voltage has to jump. An impulse current has to exist.

So, we may even in the evaluation of the initial conditions it may not be always necessary that $V_c 0 \text{ minus}$ is equal to $V_c 0 \text{ plus}$ and $I_L 0 \text{ minus}$ may not necessarily be equal to $I_L 0 \text{ plus}$. So, such cases also merit our attention. In the next lecture we will take an example or 2 of where such special initial conditions occur and then continue with our discussion of some of the elementary concepts that are needed for analysis of systems which we will make use of in our later work.