

**Course on Momentum Transfer in Process Engineering**  
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**Mod 02 Lecture 07**  
**Application of Navier Stokes Equation**

Good morning, if you remember in the previous class we had dealt with equation of continuity and equation of motion. So we developed in both R component, theta component and z component that is in the cylindrical co-ordinates that is R, theta, z we had developed, also we developed in x, y, z co-ordinate and we also get the equations for the spherical co-ordinates r, theta, phi, right.

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**R-component**

$$\rho \left[ \frac{\partial v_r}{\partial t} + v_r \frac{\partial v_r}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_r}{\partial \theta} - \frac{v_\theta^2}{r} + v_z \frac{\partial v_r}{\partial z} \right]$$

$$= \mu \left[ \frac{\partial}{\partial r} \left( \frac{1}{r} \frac{\partial}{\partial r} (r v_r) \right) + \frac{1}{r^2} \frac{\partial^2 v_r}{\partial \theta^2} - \frac{2}{r^2} \frac{\partial v_\theta}{\partial \theta} + \frac{\partial^2 v_r}{\partial z^2} \right]$$

$$- \frac{\partial p}{\partial r} + \rho g_r$$


Now the question comes in the last class if you remember in the last slides where we had given these equations of motions that is Navier-stokes equations. These equations were not so much visible the reason being, the color in mismatch with the background was not was rather there for which it was not properly visible, right and besides if we recapitulate that what was the equation then we say that it was like this in the R-component that is Rho del Vr del t plus Vr del Vr del r plus Vtheta by r del Vr del theta minus V square theta by r plus Vz del Vr del z that is equals to Mu times del del r of 1 by r del del r of r Vr plus 1 by r square del 2 Vr del theta square minus 2 by r square, this also should be del 2 Vtheta del theta square minus 2 by r square del Vtheta del theta plus del 2 Vr del z square minus del p del r plus Rho gr. This is for the R-component, right and then we proceed to this is for R, theta, z in which R-component of the equation of motion is like that.

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**θ-component**

$$\rho \left[ \frac{\partial v_\theta}{\partial t} + v_r \frac{\partial v_\theta}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_\theta}{\partial \theta} + \frac{v_r v_\theta}{r} + v_z \frac{\partial v_\theta}{\partial z} \right]$$

$$= \mu \left[ \frac{\partial}{\partial r} \frac{1}{r} \frac{\partial}{\partial r} (r v_\theta) + \frac{1}{r^2} \frac{\partial^2 v_\theta}{\partial \theta^2} + \frac{2}{r^2} \frac{\partial v_r}{\partial \theta} + \frac{\partial^2 v_\theta}{\partial z^2} \right]$$


$$- \frac{1}{r} \frac{\partial p}{\partial \theta} + \rho g_r$$


Now if you look into the other 2 components like theta component, then theta component looks like this that Rho into del Vtheta del t plus Vr del Vtheta del r plus Vtheta by r del Vtheta del theta plus Vr Vtheta over r plus Vz del Vtheta del z, this is equals to Mu times del del r of 1 by r del del r of r Vtheta plus 1 by r square del 2 Vtheta del theta square plus 2 by r square del Vr del theta plus del 2 Vtheta del z square minus 1 by r del del p del theta plus Rho gr, this is for the theta component, right.

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**Z-component**

$$\rho \left[ \frac{\partial v_z}{\partial t} + v_r \frac{\partial v_z}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_z}{\partial \theta} + v_z \frac{\partial v_z}{\partial z} \right]$$

$$= \mu \left[ \frac{1}{r} \frac{\partial}{\partial r} \left( r \frac{\partial v_z}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 v_z}{\partial \theta^2} + \frac{\partial^2 v_z}{\partial z^2} \right] - \frac{\partial p}{\partial z} + \rho g_r$$


So if R and theta is done then we left with the third component that is the z-component, r, theta, z is our co-ordinate. So if you look at that z-components looks like this, Rho times del Vz del t plus Vr del Vz del r plus Vtheta by r del Vz del theta plus Vz del Vz del z, this is

equal to  $\mu \frac{1}{r} \frac{d}{dr} \left( r \frac{dv_z}{dr} \right) + \frac{1}{r^2} \frac{d}{d\theta} \left( r^2 \frac{dv_z}{d\theta} \right) + \frac{d^2 v_z}{dz^2} - \frac{dp}{dz} + \rho g_r$ , right.

So this is these are rather all three co-ordinates or rather a three components of the co-ordinate system R, theta, z and why we recapitulated, because it was the properly seen in the previous class last slide, again I say that this was due to the mismatch of the color with the background so that was not visible; however it is rectified and now, once more reason of course is that in this is the basis of the further development further for follow up of these equations.

Now it is one of the best way of knowing the any anything is that until and unless you solve some problems you identify the parts of this equations identify individual components and then you implement it in the problem and solve the problem if you can do that then up it will appear that you have understood this equations I meaning of thus equations meaning of the individual components, how one component is affecting the other? These terms must be know and must be understood. So this is the reason we recapitulated and now we will try to solve some problem so that our understanding becomes more clear, right.

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Problem 1:- If an incompressible fluid is flowing between two vertical coaxial cylinders, and the outer one is rotating with an angular velocity  $\omega$ , determine the velocity for the tangential laminar flow.

Solution: from the physical understanding of the problem,  $v_r = v_z = 0$ , and  $\partial v_\theta / \partial \theta = 0$

From Navier Stokes equation  $-\rho v_\theta^2 / r = -\partial p / \partial r$

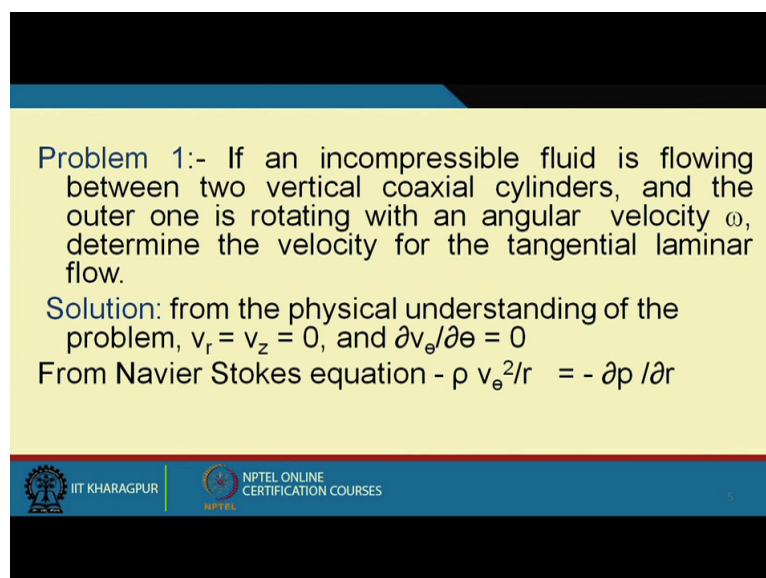
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So let us go to the problem, say if we define the problem like this, if an incompressible fluid is flowing between two vertical coaxial cylinders, and the outer one is rotating with an angular velocity of omega then determine the velocity for the tangential laminar flow. I repeat if an incompressible fluid, so here we are taking the fluid to be incompressible is flowing between two vertical coaxial cylinders right, so we have to cylinders, so one cylinder like this

and the other cylinder like this, these two cylinders are there and the outer one is rotating with an angular velocity of  $\omega$ , so if this is the outer one, so this is the inner one, so inner value is fix, outer value is rotating with and angular velocity of  $\omega$  then determine the velocity for the tangential laminar flow, right.

Now given this problem here we assume one thing that the flow is steady there is no unsteady component then, because we as we said that this is the outer one and this is the inner one, inner one is fixed outer one is rotating with an angular velocity of  $\omega$  if that is there then the fluid inside between this two that is in the  $(r, \theta, z)$  space how the velocity profile what is the momentum distribution that if we find out then we will be able to understand and use the Navier-stokes equations properly, right. So for this, what we need to know first, what is the problem theoretically given and how it looks like on paper.

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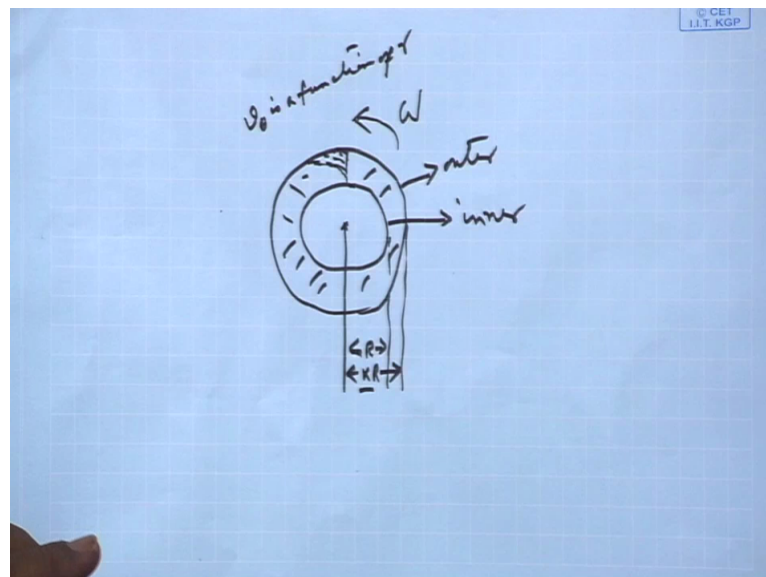
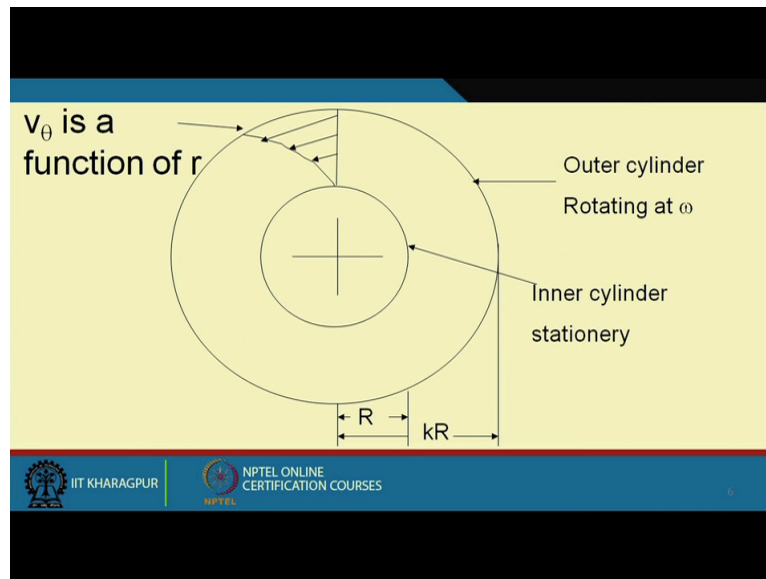


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Now if you look at this, what we are given that we have two cylinders, this is the outer cylinder and this is the inner cylinder, right. So outer cylinder and inner cylinder, so if this is the inner cylinder and if this is the outer cylinder, right and if this is the center then we have the radii as this one is  $R$  and this one is some multiple of  $R$  say  $kR$ ., right. So if this is true then of course this is the outer cylinder and this is the inner cylinder, right and we said that it will have an angular velocity of  $\omega$ , right.


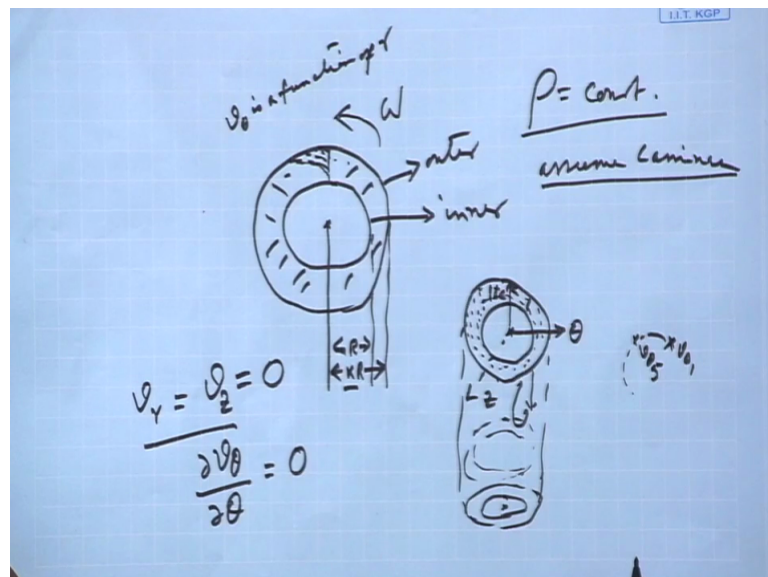
So if we look at the velocity component we will look into this looks like this, right where this  $V_{\theta}$  is function of  $r$ , right. So this and inner cylinder has an has as radius of  $R$  and the outer cylinder has the radius of a multiple of say  $kR$ . What that  $k$  is unknown;  $k$  is a constant which we do not know. So it can be anything twice of  $R$ , half of  $R$ ,  $0.3$  of  $R$ ,  $1.8$  of  $R$  whatever value you can assign too, right. So it does not matter, so we have to find out this. So this problem if

again I am repeating that this is the outer cylinder, this is the inner cylinder and the fluid inside is air, right and this what we said, this inner cylinder is fixed and out outer cylinder suddenly started rotating with an angular momentum of  $\rho \omega$ . So at steady state, what is the velocity distribution and what is the momentum profile that if we can find out or say shear stress component that if we can find out then we will be able to understand how the Navier-stokes equation can be utilized to solve this kind of problem, right.

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Solution: from the physical understanding of the problem,  $v_r = v_z = 0$ , and  $\partial v_\theta / \partial \theta = 0$   
 From Navier Stokes equation  $-\rho v_\theta^2 / r = -\partial p / \partial r$

So if we look at whatever is given, now from this problem what we understand that number 1, it is incompressible fluid, so  $\rho$  is constant, right. It is incompressible fluid  $\rho$  is constant if  $\rho$  is constant then many factors will go out, number 1. Number 2, we said that there is this flow is of course we assume to be laminar, right. Why you are assuming it to be

laminar? If we again look into this, this is there and this is the outer. So the layers which are like this, right layers which are like this, these are the liquid layers when they are moving like this, this interaction between the layers is not there, so that is why we assume it to be laminar that if we assume the flow to be laminar we assume that the density of the fluid is constant then if that be true then there is no interaction between the layers. So when there is no interaction between the layers that means one layer with the other layer, they are not having any mutual interaction, right. They are just moving to  $(13:32)$  freely and this we have depicted like this, right okay.

Now if that be true from this condition we can say that  $V_r$  is equals to  $V_z$  that means there is no velocity in the R-component, right. In the R direction have there been any velocity then it would have mix like this, right which it is not because we assume that there is a stream line like this as it will can right. So these stream lines are  $(14:19)$  there, there is no R component.

Similarly and if this is the R the other one is theta and the third one is z, right. Similarly this is one and you in just extend it like this, okay if this is the z component, right. So this is the z component, so there is no no vertical, there is no horizontal that flow since R is the or R component of the velocity is not there. Similarly z component of the velocity is also not there that is there is no mixing within the fluid, right. So that is what we know it to be laminar. So like this then another like this. So these kinds of layers are there, so that is one layer is not mixing with the other. So that is why we can assume we can say the  $V_r$  is equals to  $V_z$  and that is equals to zero and also here, one is must say that this seems this is moving like this. Now since this is moving like this, this one is not going and mixing with that one, right. So this there is no velocity component in the theta direction also. This is the theta direction.

So there is no velocity component in the theta direction also, so in that case we can say  $\frac{\partial V_\theta}{\partial \theta}$  is equals to zero, because this theta component or  $V_\theta$  say 1 and say this  $V_\theta$  of say 5 is not they are one is over the other, there is not mixing of this  $V_\theta$  also, right  $V_\theta 1$  and  $V_\theta 5$  we can whatever be the value remaining  $(16:49)$  the same and there is no change in the theta component in this direction, right. So that is why we can say  $\frac{\partial V_\theta}{\partial \theta}$  is zero if this is true then we if we remember that the Navier-stokes equation which we had originally given, right.

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### $\theta$ -component

$$\begin{aligned} & \rho \left[ \frac{\partial v_\theta}{\partial t} + v_r \frac{\partial v_\theta}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_\theta}{\partial \theta} + \frac{v_r v_\theta}{r} + v_z \frac{\partial v_\theta}{\partial z} \right] \\ &= \mu \left[ \frac{\partial}{\partial r} \left( \frac{1}{r} \frac{\partial}{\partial r} (r v_\theta) \right) + \frac{1}{r^2} \frac{\partial^2 v_\theta}{\partial \theta^2} + \frac{2}{r^2} \frac{\partial v_r}{\partial \theta} + \frac{\partial^2 v_\theta}{\partial z^2} \right] \\ & \quad - \frac{1}{r} \frac{\partial p}{\partial \theta} + \rho g_r \end{aligned}$$



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### R-component

$$\begin{aligned} & \rho \left[ \frac{\partial v_r}{\partial t} + v_r \frac{\partial v_r}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_r}{\partial \theta} - \frac{v_\theta^2}{r} + v_z \frac{\partial v_r}{\partial z} \right] \\ &= \mu \left[ \frac{\partial}{\partial r} \left( \frac{1}{r} \frac{\partial}{\partial r} (r v_r) \right) + \frac{1}{r^2} \frac{\partial^2 v_r}{\partial \theta^2} - \frac{2}{r^2} \frac{\partial v_\theta}{\partial \theta} - \frac{2}{r^2} \frac{\partial v_r}{\partial \theta} + \frac{\partial^2 v_r}{\partial z^2} \right] \\ & \quad - \frac{\partial p}{\partial r} + \rho g_r \end{aligned}$$



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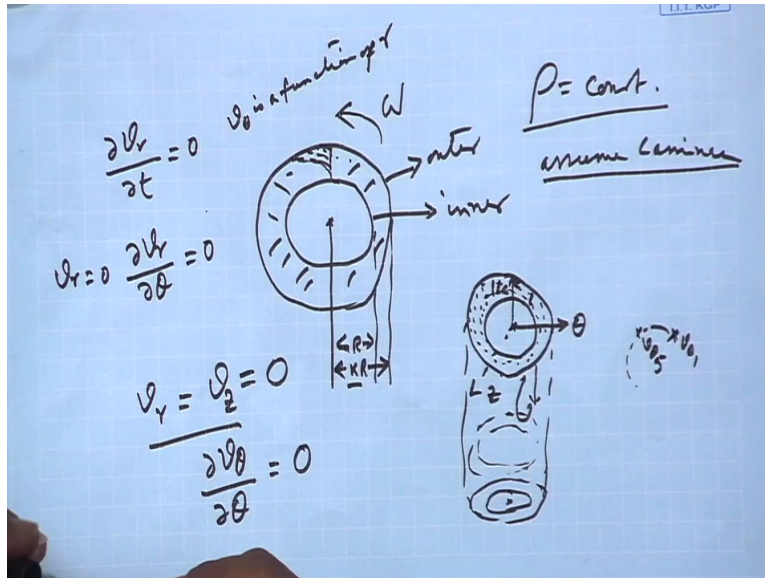


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R-component

$$\rho \left[ \frac{\partial v_r}{\partial t} + v_r \frac{\partial v_r}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_r}{\partial \theta} - \frac{v_\theta^2}{r} + v_z \frac{\partial v_r}{\partial z} \right]$$

$$= \mu \left[ \frac{\partial}{\partial r} \left( \frac{1}{r} \frac{\partial}{\partial r} (r v_r) \right) + \frac{1}{r^2} \frac{\partial^2 v_r}{\partial \theta^2} - \frac{2}{r^2} \frac{\partial v_\theta}{\partial \theta} - \frac{2}{r^2} \frac{\partial v_\theta}{\partial \theta} + \frac{\partial^2 v_r}{\partial z^2} \right]$$

$$- \frac{\partial p}{\partial r} + \rho g_r$$

So this is the R component and in R component  $V_r$  is zero, first  $\rho$  constant and also it is under steady state, so  $\frac{\partial V_r}{\partial t}$  this is also zero,  $\frac{\partial V_r}{\partial t}$  is zero  $\rho$  is constant, right. So we can say that this component  $\frac{\partial V_r}{\partial t}$  is zero,  $V_r$  is zero. So this component goes out, right  $\frac{\partial V_r}{\partial \theta}$ , right  $\frac{\partial V_r}{\partial \theta}$  that is change in  $V_r$  with  $\theta$ . So that can be there, so that is why we can say  $\rho \frac{v_\theta^2}{r}$  by  $r \frac{\partial V_r}{\partial \theta} \frac{\partial V_r}{\partial \theta}$  if there been any  $V_r$  component also with the  $\theta$ , right. With (18:21) the  $\theta$  direction change in  $\theta$  with  $V_r$  that is not also there. So we can say since  $V_r$  is zero, so  $\frac{\partial V_r}{\partial \theta}$  is also zero  $V_r$  is zero, right. So we can say this component also is not there minus  $\frac{v_\theta^2}{r}$ . So it remains, so it is  $\rho \frac{v_\theta^2}{r}$  with negative. Now  $V_z$  is also zero, so this component remains zero then, this is equals to  $\mu \frac{\partial}{\partial r} \left( \frac{1}{r} \frac{\partial}{\partial r} (r v_r) \right)$  since  $V_r$  is zero. So this again is zero  $\frac{\partial^2 V_r}{\partial \theta^2}$ , since  $V_r$  is zero then  $\frac{\partial^2 V_\theta}{\partial \theta^2}$  or  $V_r \frac{\partial^2 V_\theta}{\partial \theta^2}$  that remains zero. Then since  $\frac{\partial V_\theta}{\partial \theta}$  that also is

zero. So this term also is not there then this term  $\frac{\partial v_\theta}{\partial t}$  is also not there and since  $v_r$  is zero, so  $\frac{\partial^2 v_r}{\partial z^2}$  is zero, but minus  $\frac{\partial p}{\partial r} + \rho g_r$  is there.



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**R-component**

$$\rho \left[ \frac{\partial v_r}{\partial t} + v_r \frac{\partial v_r}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_r}{\partial \theta} - \frac{v_\theta^2}{r} + v_z \frac{\partial v_r}{\partial z} \right]$$

$$= \mu \left[ \frac{\partial}{\partial r} \left( \frac{1}{r} \frac{\partial}{\partial r} (r v_r) \right) + \frac{1}{r^2} \frac{\partial^2 v_r}{\partial \theta^2} - \frac{2}{r^2} \frac{\partial v_\theta}{\partial \theta} - \frac{2}{r^2} \frac{\partial v_\theta}{\partial \theta} + \frac{\partial^2 v_r}{\partial z^2} \right]$$

$$- \frac{\partial p}{\partial r} + \rho g_r$$



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**$\theta$ -component**

$$\rho \left[ \frac{\partial v_\theta}{\partial t} + v_r \frac{\partial v_\theta}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_\theta}{\partial \theta} + \frac{v_r v_\theta}{r} + v_z \frac{\partial v_\theta}{\partial z} \right]$$

$$= \mu \left[ \frac{\partial}{\partial r} \left( \frac{1}{r} \frac{\partial}{\partial r} (r v_\theta) \right) + \frac{1}{r^2} \frac{\partial^2 v_\theta}{\partial \theta^2} + \frac{2}{r^2} \frac{\partial v_r}{\partial \theta} + \frac{\partial^2 v_\theta}{\partial z^2} \right]$$

$$- \frac{1}{r} \frac{\partial p}{\partial \theta} + \rho g_\theta$$

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### Z-component

$$\rho \left[ \frac{\partial v_z}{\partial t} + v_r \frac{\partial v_z}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_z}{\partial \theta} + v_z \frac{\partial v_z}{\partial z} \right]$$

$$= \mu \left[ \frac{1}{r} \frac{\partial}{\partial r} \left( r \frac{\partial v_z}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 v_z}{\partial \theta^2} + \frac{\partial^2 v_z}{\partial z^2} \right] - \frac{\partial p}{\partial z} + \rho g_r$$



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From Navier Stokes equation  $-\rho v_\theta^2 / r = -\partial p / \partial r$



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Similarly this is if that is true then we can write that for the first equation minus  $\rho v_\theta^2 / r$  that is equals to minus  $\partial p / \partial r$ . So here one thing is the  $\rho g_r$ , right  $\rho g_r$  that is the gravitational value  $g_r$  since  $r$  is there we assume that  $g_r$  is negligible and  $g_r$  component is not there, right. So we than get that minus  $\rho v_\theta^2 / r$  into  $v_\theta^2 / r$ . This is equals to minus  $\partial p / \partial r$ , right  $\rho g_r$  is assume to be negligible and that can be neglected.




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### θ-component

$$\rho \left[ \frac{\partial v_\theta}{\partial t} + v_r \frac{\partial v_\theta}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_\theta}{\partial \theta} + \frac{v_r v_\theta}{r} + v_z \frac{\partial v_\theta}{\partial z} \right]$$

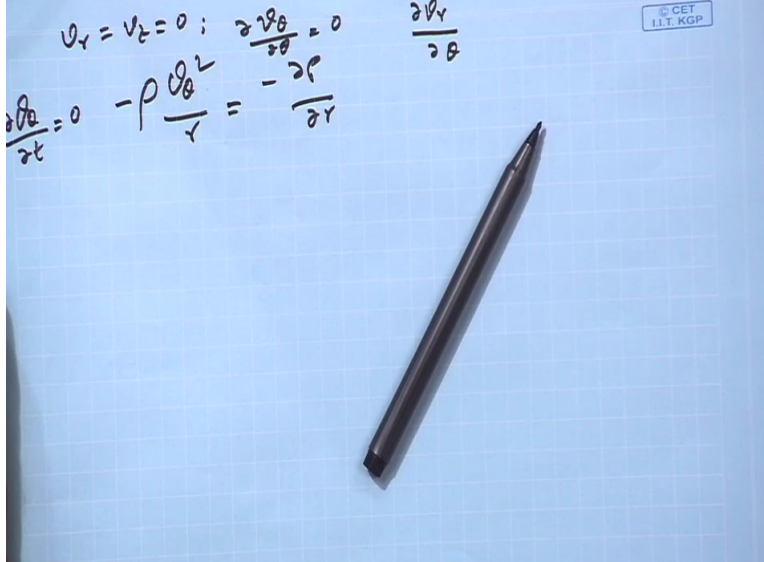
$$= \mu \left[ \frac{\partial}{\partial r} \frac{1}{r} \frac{\partial}{\partial r} (r v_\theta) + \frac{1}{r^2} \frac{\partial^2 v_\theta}{\partial \theta^2} + \frac{2}{r^2} \frac{\partial v_r}{\partial \theta} + \frac{\partial^2 v_\theta}{\partial z^2} \right]$$

$$-\frac{1}{r} \frac{\partial p}{\partial \theta} + \rho g_r$$

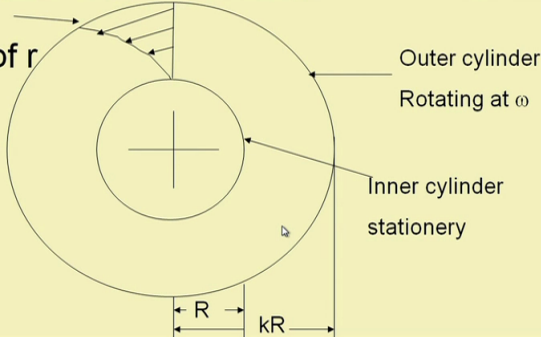

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$v_r = v_z = 0; \frac{\partial v_\theta}{\partial \theta} = 0$   
 $\frac{\partial v_\theta}{\partial t} = 0 \quad -\rho \frac{v_\theta^2}{r} = -\frac{\partial p}{\partial r}$   
 $\frac{\partial v_r}{\partial \theta}$





$v_\theta$  is a function of  $r$



Outer cylinder  
Rotating at  $\omega$

Inner cylinder  
stationery

$R \quad kR$




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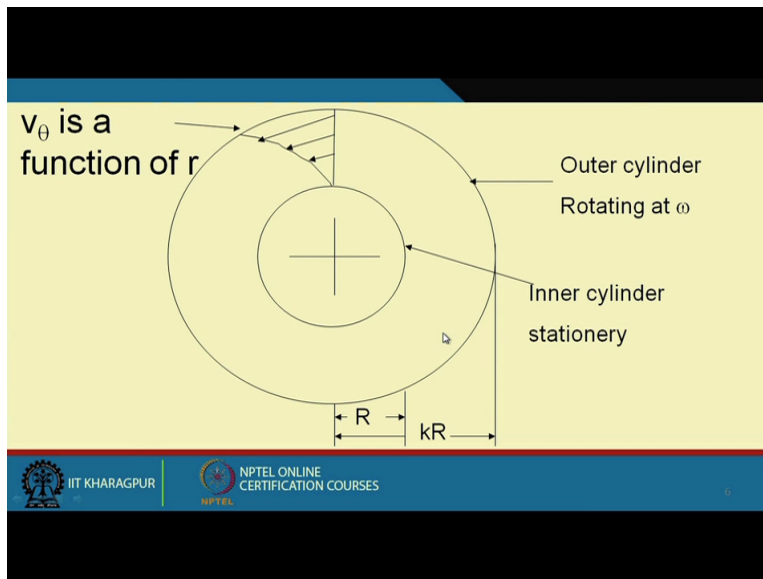
So if this is r component, similarly for theta component we can say stay on the same way since Rho is constant and since it is steady state. So we can say that  $\frac{\partial v_{\theta}}{\partial t}$  is equals to zero, right we also said  $v_r$  is equals to  $v_z$  is equal to zero, this was our initial  $\frac{\partial v_{\theta}}{\partial r}$   $\frac{\partial v_{\theta}}{\partial \theta}$  was also equals to zero, right. So if that be true then we can write  $\frac{\partial v_{\theta}}{\partial r}$ , right  $v_r$  into  $\frac{\partial v_{\theta}}{\partial r}$  that is there. So  $v_{\theta}$  by r  $\frac{\partial v_{\theta}}{\partial \theta}$  that goes out then  $v_r v_{\theta}$  v over r since  $v_r$  is zero, so that it goes out. So this goes out  $v_z$  is zero this goes out right  $v_r$  is zero. So this also goes out but  $v_{\theta}$  by r  $\frac{\partial v_{\theta}}{\partial \theta}$ . So this goes zero, so this is zero this is zero this is zero this is zero and this is also zero.

So left side is zero, right side is  $\mu \frac{\partial}{\partial r} \left( \frac{1}{r} \frac{\partial}{\partial r} (r v_{\theta}) \right)$ , right which (()) (22:21) the function of r. So this results, so one by r square  $\frac{\partial^2 v_{\theta}}{\partial \theta^2}$  square. So since  $\frac{\partial v_{\theta}}{\partial \theta}$  is zero. So  $\frac{\partial^2 v_{\theta}}{\partial \theta^2}$  square is also zero. So this term goes out. The third one  $\frac{\partial v_r}{\partial \theta}$  right, So 2 by r square  $\frac{\partial v_r}{\partial \theta}$ . So this for this is  $v_r$  that is R component of the velocity  $v_r v_{\theta}$   $\frac{\partial v_{\theta}}{\partial r}$   $\frac{\partial v_r}{\partial \theta}$ , right. So this also goes out, because since  $v_r$  is only function of r so 2 by r square  $\frac{\partial v_r}{\partial \theta}$  okay, now  $\frac{\partial v_r}{\partial \theta}$  this can be there, right. So this can be there.

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$0 = \frac{\partial}{\partial r} \left( \frac{1}{r} \frac{\partial}{\partial r} (r v_{\theta}) \right)$   
 and  $0 = -\frac{\partial p}{\partial z} + \rho g_z$   
 from the eq<sup>n</sup>,  $\frac{\partial}{\partial r} \left( \frac{1}{r} \frac{\partial}{\partial r} (r v_{\theta}) \right) = 0$   
 or,  $\frac{1}{r} \frac{\partial}{\partial r} (r v_{\theta}) = A$   
 or,  $\frac{\partial}{\partial r} (r v_{\theta}) = A r$   
 or,  $r v_{\theta} = A r^2/2 + B$   
 or,  $v_{\theta} = A r/2 + B/r$   
 Applying B.C,  
 $v_{\theta} = 0$ , at  $r = R$ ;      and  $v_{\theta} = \omega r$  at  $r = kR$   
 $0 = A R/2 + B/R$   
 and  $\omega kR = A kR/2 + B/kR$

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Problem 1:- If an incompressible fluid is flowing between two vertical coaxial cylinders, and the outer one is rotating with an angular velocity  $\omega$ , determine the velocity for the tangential laminar flow.

Solution: from the physical understanding of the problem,  $v_r = v_z = 0$ , and  $\partial v_\theta / \partial \theta = 0$

From Navier Stokes equation  $-\rho v_\theta^2 / r = -\partial p / \partial r$



Z-component

$$\rho \left[ \frac{\partial v_z}{\partial t} + v_r \frac{\partial v_z}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_z}{\partial \theta} + v_z \frac{\partial v_z}{\partial z} \right]$$

$$= \mu \left[ \frac{1}{r} \frac{\partial}{\partial r} \left( r \frac{\partial v_z}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 v_z}{\partial \theta^2} + \frac{\partial^2 v_z}{\partial z^2} \right] - \frac{\partial p}{\partial z} + \rho g_r$$






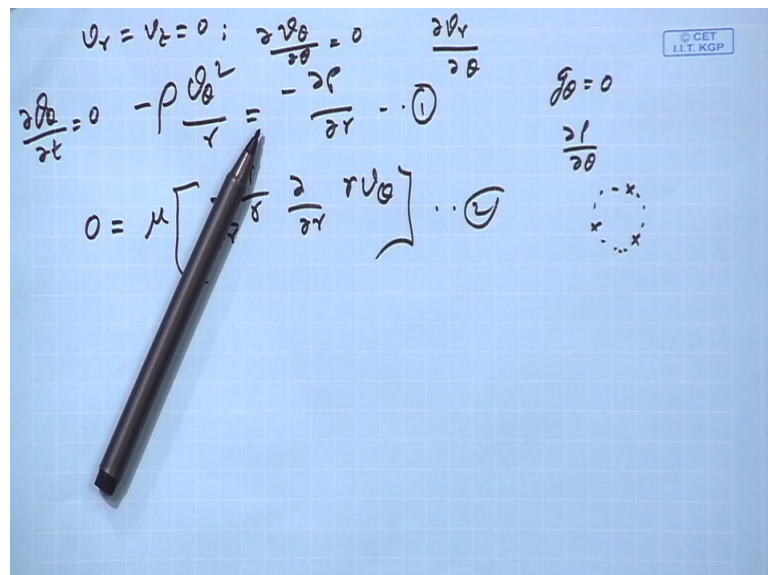
### θ-component

$$\rho \left[ \frac{\partial v_\theta}{\partial t} + v_r \frac{\partial v_\theta}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_\theta}{\partial \theta} + \frac{v_r v_\theta}{r} + v_z \frac{\partial v_\theta}{\partial z} \right]$$

$$= \mu \left[ \frac{\partial}{\partial r} \frac{1}{r} \frac{\partial}{\partial r} (r v_\theta) + \frac{1}{r^2} \frac{\partial^2 v_\theta}{\partial \theta^2} + \frac{2}{r^2} \frac{\partial v_r}{\partial \theta} + \frac{\partial^2 v_\theta}{\partial z^2} \right]$$

$$-\frac{1}{r} \frac{\partial p}{\partial \theta} + \rho g_r$$


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So second one this  $\frac{\partial v_\theta}{\partial \theta}$  is there. So theta component  $v_r^2$  by  $r^2$  is there  $\frac{\partial v_r}{\partial \theta}$ ,  $v_r$  is zero, right. So  $\frac{\partial v_r}{\partial \theta}$  is zero, so  $\frac{2}{r^2} \frac{\partial v_r}{\partial \theta}$  is also out and the  $\frac{\partial^2 v_\theta}{\partial z^2}$ , since it is the double derivative and there is no  $v_\theta$   $v_z$  component. So that is also zero, so we can write and remaining  $\frac{1}{r} \frac{\partial p}{\partial \theta}$  plus  $\rho g_r$ .

Now here you  $\rho g_\theta$  sorry, this will be  $\rho g_\theta$  as I said that there be some (24:28) mistakes, so here it should have been  $\rho g_\theta$ , right. Now here also  $\frac{\partial p}{\partial \theta}$  we can assume to be zero and  $\frac{\partial p}{\partial \theta}$  what does it mean? A physically  $\frac{\partial p}{\partial \theta}$ , so pressure with the theta. So this is the theta component, so whatever pressure is here same pressure is there the assume pressure is there. So  $\frac{\partial p}{\partial \theta}$  from the physical understanding is also zero. Now so we cannot say that  $\frac{\partial p}{\partial \theta}$  is also there. Then we





get the from their left hand side is equals to zero, because all these components have been zero. So zero is equals to Mu del del r of r 1 by r del del r of 1 by r del del r of r Vtheta, this is the second equation.

The first equation we got there as to remember (25:50) that it was Rho minus Mu minus Mu ya this was Rho Vtheta square, this that is Rho Vtheta square by r is del p del r right, but here that it is zero Mu this is the second and the third component if we look at is Rho is constant Vz is zero. So V and not only Vz zero del t is also not there that is it is not (26:28) with type, so del Vz del t is zero Vr is zero.

(Refer Slide Time: 26:36)

Z-component

$$\rho \left[ \frac{\partial v_z}{\partial t} + v_r \frac{\partial v_z}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_z}{\partial \theta} + v_z \frac{\partial v_z}{\partial z} \right]$$


$$= \mu \left[ \frac{1}{r} \frac{\partial}{\partial r} \left( r \frac{\partial v_z}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 v_z}{\partial \theta^2} + \frac{\partial^2 v_z}{\partial z^2} \right] - \frac{\partial p}{\partial z} + \rho g_r$$





$v_r = v_z = 0; \frac{\partial v_\theta}{\partial \theta} = 0 \quad \frac{\partial v_r}{\partial \theta}$

$\frac{\partial v_\theta}{\partial t} = 0 \quad -\rho \frac{v_\theta^2}{r} = -\frac{\rho v_\theta^2}{r} \quad \dots \textcircled{1}$

$0 = \mu \left[ \frac{\partial}{\partial r} \left( \frac{1}{r} \frac{\partial}{\partial r} (r v_\theta) \right) \right] \dots \textcircled{2}$

$0 = -\frac{\partial p}{\partial z} + \rho g_z \dots \textcircled{3}$



So del Vtheta del Vtheta del Vz del theta this is also zero, because Vz is zero Vz this term is also zero Mu one by r del del r of r Vz del Vz del r, so Vz V zero this term will goes out del 2


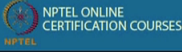



$v_z$  del theta square. This was also zero del  $^2 v_z$  del z square is zero, but minus del p del z plus Rho gr, this term is again where it should be Rho gz, right. So this term is there, so we can write zero is equals to minus del p del z plus Rho gz, this is equation 3, right. So we need to find out  $v_{\theta}$ , so only one equation is good (27:32), because one unknown other  $\mu$  is known for a given (27:38), right r is known for the given diameter of the cylinder. So if they are known then with unknown is  $v_{\theta}$ .

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Z-component


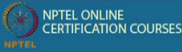
$$\rho \left[ \frac{\partial v_z}{\partial t} + v_r \frac{\partial v_z}{\partial r} + \frac{v_{\theta}}{r} \frac{\partial v_z}{\partial \theta} + v_z \frac{\partial v_z}{\partial z} \right]$$

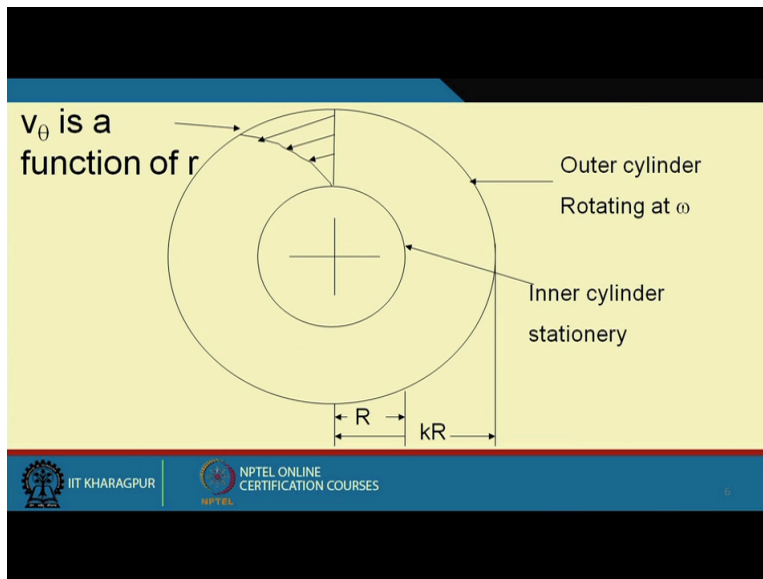
$$= \mu \left[ \frac{1}{r} \frac{\partial}{\partial r} \left( r \frac{\partial v_z}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 v_z}{\partial \theta^2} + \frac{\partial^2 v_z}{\partial z^2} \right] - \frac{\partial p}{\partial z} + \rho g_r$$




Problem 1:- If an incompressible fluid is flowing between two vertical coaxial cylinders, and the outer one is rotating with an angular velocity  $\omega$ , determine the velocity for the tangential laminar flow.

Solution: from the physical understanding of the problem,  $v_r = v_z = 0$ , and  $\partial v_{\theta} / \partial \theta = 0$

From Navier Stokes equation -  $\rho v_{\theta}^2 / r = - \partial p / \partial r$



$$0 = \frac{\partial}{\partial r} \left( \frac{1}{r} \frac{\partial}{\partial r} (r v_\theta) \right)$$

and  $0 = -\frac{\partial p}{\partial z} + \rho g_z$

from the eq<sup>n</sup>,  $\frac{\partial}{\partial r} \left( \frac{1}{r} \frac{\partial}{\partial r} (r v_\theta) \right) = 0$

or,  $\frac{1}{r} \frac{\partial}{\partial r} (r v_\theta) = A$

or,  $\frac{\partial}{\partial r} (r v_\theta) = A r$

or,  $r v_\theta = A r^2/2 + B$

or,  $v_\theta = A r/2 + B/r$

Applying B.C,

$v_\theta = 0$ , at  $r = R$ ;      and  $v_\theta = \omega k r$  at  $r = kR$

$0 = A R/2 + B/R$

and  $\omega k r = A k R/2 + B/kR$

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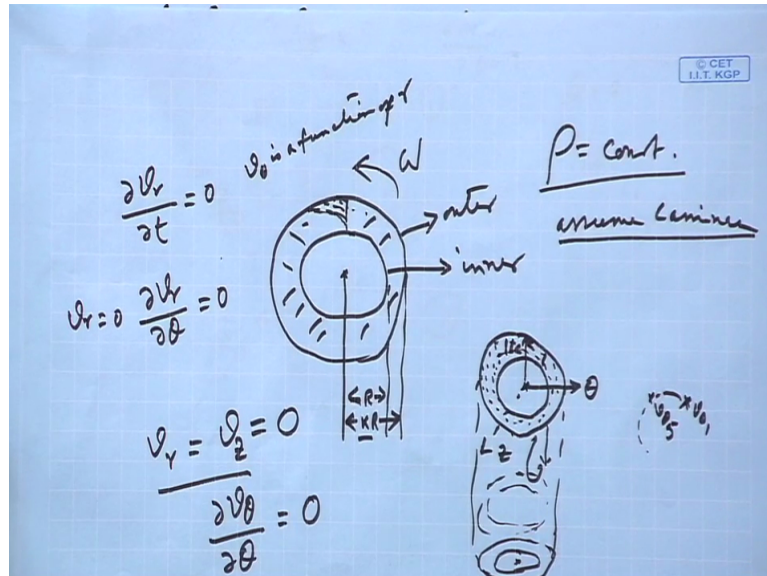
$v_r = v_z = 0$ ;  $\frac{\partial v_\theta}{\partial \theta} = 0$        $\frac{\partial v_r}{\partial \theta} = 0$

$\frac{\partial v_\theta}{\partial t} = 0$        $-\rho \frac{\partial v_\theta}{\partial r} = -\frac{\partial p}{\partial r}$       ①



$0 = \mu \left[ \frac{\partial}{\partial r} \left( \frac{1}{r} \frac{\partial}{\partial r} (r v_\theta) \right) \right]$       ②

$0 = -\frac{\partial p}{\partial z} + \rho g_z$       ③

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$0 = \frac{\partial}{\partial r} (1/r (\frac{\partial}{\partial r} (rv_\theta)))$   
 and  $0 = -\frac{\partial p}{\partial z} + \rho g_z$   
 from the eq<sup>n</sup>,  $\frac{\partial}{\partial r} (1/r (\frac{\partial}{\partial r} (rv_\theta))) = 0$   
 or,  $1/r (\frac{\partial}{\partial r} (rv_\theta)) = A$   
 or,  $\frac{\partial}{\partial r} (rv_\theta) = A r$   
 or,  $rv_\theta = A r^2/2 + B$   
 or,  $v_\theta = A r/2 + B/r$   
 Applying B.C,  
 $v_\theta = 0$ , at  $r = R$ ;      and  $v_\theta = \omega r$  at  $r = kR$   
 $0 = A R/2 + B/R$   
 and  $\omega kR = A kR/2 + B/kR$

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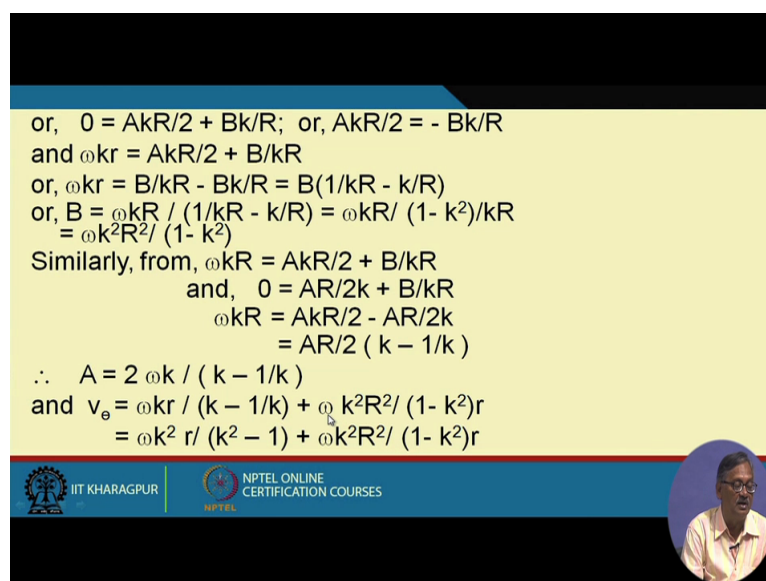
So to find out this  $V_\theta$  unknown if we solve this problem then we can say that which start (())(28:01) that second equation that is zero is equal to  $\frac{\partial}{\partial r} (\frac{1}{r} \frac{\partial}{\partial r} (r V_\theta))$ , right an second equation which we got that was minus  $\frac{\partial p}{\partial z} + \rho g_z$  this one, right. So this one was the and the third one which we had already shown that minus  $\rho V_\theta^2$  by  $r$  is equals to minus  $\frac{\partial p}{\partial r}$ , right. This out of these three equations let us start with the second equation that  $\frac{\partial}{\partial r} (\frac{1}{r} \frac{\partial}{\partial r} (r V_\theta))$  is equals to zero on first integration it gives one by  $r \frac{\partial}{\partial r} (r V_\theta)$  that is equals to  $r$  integral constant, so A.

So on simplification this can be writurn that  $\frac{\partial}{\partial r} (r V_\theta)$  is equals to  $A r$ , right. So on again second integration we can say  $r V_\theta$  is equals to  $A r^2/2 + B$  which on simplification can be writurn that  $V_\theta$  is equals to  $A r/2 + B/r$ , right. Now we have two equations and two boundary constants that is integral constant B and C, right. So we

have to find out what is the A and B what is the boundary. Boundary is  $V_{\theta}$  is equals to zero at  $r$  is equals to  $r$  that is what we have been said  $V_{\theta}$  is equals to zero  $r$  is equals to  $r$ , this at  $r$  is equals to  $r$  if this is constant. So  $V_{\theta}$  is equals to zero at  $r$  is equals to  $r$ . so in that case we can write then the second is the outer cylinder is rotating with an angular velocity of  $\omega$ .

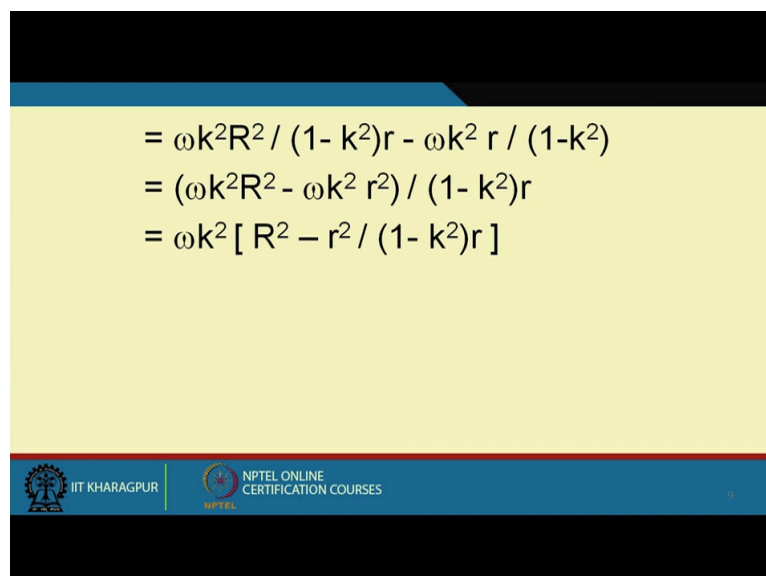
So we can say  $V_{\theta}$  is equals to  $\omega k r$  at  $r$  is equals to  $KR$ . So using these two boundaries and solving we can write zero is equals to  $AR$  by 2 plus  $B$  by  $R$  and  $\omega k r$  is equals to  $AkR$  by 2 plus  $B$  by  $kR$ .

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or,  $0 = AkR/2 + Bk/R$ ; or,  $AkR/2 = - Bk/R$   
 and  $\omega k r = AkR/2 + B/kR$   
 or,  $\omega k r = B/kR - Bk/R = B(1/kR - k/R)$   
 or,  $B = \omega k r / (1/kR - k/R) = \omega k r / (1 - k^2)/kR$   
 $= \omega k^2 R^2 / (1 - k^2)$   
 Similarly, from,  $\omega k R = AkR/2 + B/kR$   
 and,  $0 = AR/2k + B/kR$   
 $\omega k R = AkR/2 - AR/2k$   
 $= AR/2 (k - 1/k)$   
 $\therefore A = 2 \omega k / (k - 1/k)$   
 and  $v_{\theta} = \omega k r / (k - 1/k) + \omega k^2 R^2 / (1 - k^2) r$   
 $= \omega k^2 r / (k^2 - 1) + \omega k^2 R^2 / (1 - k^2) r$

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$$= \omega k^2 R^2 / (1 - k^2) r - \omega k^2 r / (1 - k^2)$$

$$= (\omega k^2 R^2 - \omega k^2 r^2) / (1 - k^2) r$$

$$= \omega k^2 [ R^2 - r^2 / (1 - k^2) r ]$$

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So in that case we have these two equations zero is equals to  $AkR$  by 2 plus  $Bk$  by  $R$  and  $AkR$  by 2 is equals to minus  $Bk$  by  $R$  and  $\omega k R$  is equals to  $AkR$  by 2 plus  $b$  by  $kR$ . So on

simplification and solving we can write  $\omega kR$  is equals to  $B$  by  $kR$  minus  $Bk$  by  $R$  that is equals to  $B$  into  $1$  by  $kR$  minus  $k$  by  $R$  that is equals to in that case we can say  $B$  is equals to  $\omega kR$  by  $1$  by  $kR$  minus  $k$  by  $R$ , this is equals to  $\omega kR$  by  $1$  minus  $K$  square by  $kR$  that must be is equal to  $\omega k$  square  $R$  square by  $1$  minus  $k$  square. So similarly from that equation  $\omega kR$  is equals to be  $kR$  by two plus  $B$  by  $kR$ .

So from there we can write zero is equals to  $AR$  by  $2$  plus  $AR$  by  $2k$  plus  $B$  by  $kR$  and  $\omega kR$  is equals to  $AkR$  by  $2$  minus  $AR$  by  $2k$  that is equals to  $AR$  by  $2$  into  $k$  into  $1$  minus  $1$  by  $k$ . So in that case  $A$  becomes  $2\omega k$  over  $k$  minus  $1$  by  $k$ . So  $V_{\theta}$  can be writurn as  $\omega kR$ . by  $k$  minus  $1$  by  $k$  plus  $\omega k$  square  $R$  square into  $1$  minus  $k$  square into  $R$  that is  $\omega k$  square  $R$  over  $k$  square minus  $1$  plus  $\omega k$  square  $R$  square over  $1$  minus  $k$  square. So this on simplification gives  $\omega k$  square  $r$  square by  $1$  minus  $k$  square into  $R$  minus  $\omega k$  square  $R$  by  $1$  minus  $k$  square. So  $\omega k$  square  $R$  square minus  $\omega k$  square  $R$  square over that was capital  $R$ , this small  $r$   $1$  minus  $k$  square  $r$  so this means on simplification we can write  $\omega k$  square into  $R$  square minus  $r$  square over  $1$  minus  $k$  square into  $r$ . So  $V_{\theta}$  is equals to the  $\omega k$  square  $R$  square minus  $r$  square  $1$  minus  $k$  square  $r$ . So we have come down from the problem and understanding of the problem what is the velocity component which is acting in the theta direction, right.

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Example 2: A cylindrical container of radius  $R$  containing a fluid of constant density and viscosity is caused to rotate about its own axis at an angular velocity  $\Omega$ . The cylinder axis is vertical. Find the shape of the free surface at steady state.

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Solution:- Since the cylinder axis is vertical,  $g_r = g_\theta = 0$  and,  $g_z = -g$ .

From equations of change and the understanding of the problem:

$v_r = v_z = 0$ ;  $v_\theta = f(r)$ ; and  $\partial v_\theta / \partial \theta = 0$   
 r-component,  $\rho v_\theta^2 / r = \partial p / \partial r$   
 $\theta$ -component,  $0 = \mu \partial / \partial r (1/r (\partial / \partial r (r v_\theta)))$   
 z-component,  $0 = -\partial p / \partial z - \rho g$   
 from integration of the  $\theta$ -component,  
 $1/r (\partial / \partial r (r v_\theta)) = A$   
 or,  $\partial / \partial r (r v_\theta) = A r$

on integration,  $p = \rho \Omega^2 r^2 / 2 - \rho g z + c$   
 from the problem, the b.c. is,  $p = p_0$  at  $z = z_0$  and  $r = 0$

or,  $p_0 = -\rho g z_0 + c$

or,  $c = p_0 + \rho g z_0$

$\therefore p = \rho \Omega^2 r^2 / 2 + p_0 + \rho g z_0 - \rho g z$

or,  $p - p_0 = \rho \Omega^2 r^2 / 2 + \rho g (z_0 - z)$

Since,  $p - p_0 = 0$  at all points on the surface,  $g (z - z_0) = \Omega^2 r^2 / 2$   
 $(z - z_0) = \Omega^2 r^2 / 2g$

So this way if you solve many problems you try the other one. In this case what we have given that inner one is fixed and the outer one is rotating. Now you try to do that the inner one is rotating and the outer one is fixed. So inner one rotating in that case what will be the velocity component in the theta directions. So when it there is no  $V_r$  there is no  $V_z$ , because we assumed it to be say laminar (( ))(33:45), so that is why there is no  $V_r$  there is no  $V_z$  as an it is steady state.

So del t part is also not there. So implementing all these you can find out how the equation of motions that is Navier stoke can be utilized, obviously we will do some more problem otherwise it really difficult it will be to implement and understand, okay. So that is why we do here for this class, thank you.